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Machine Learning for Hyper-Kamiokande's Water-Cherenkov Detectors

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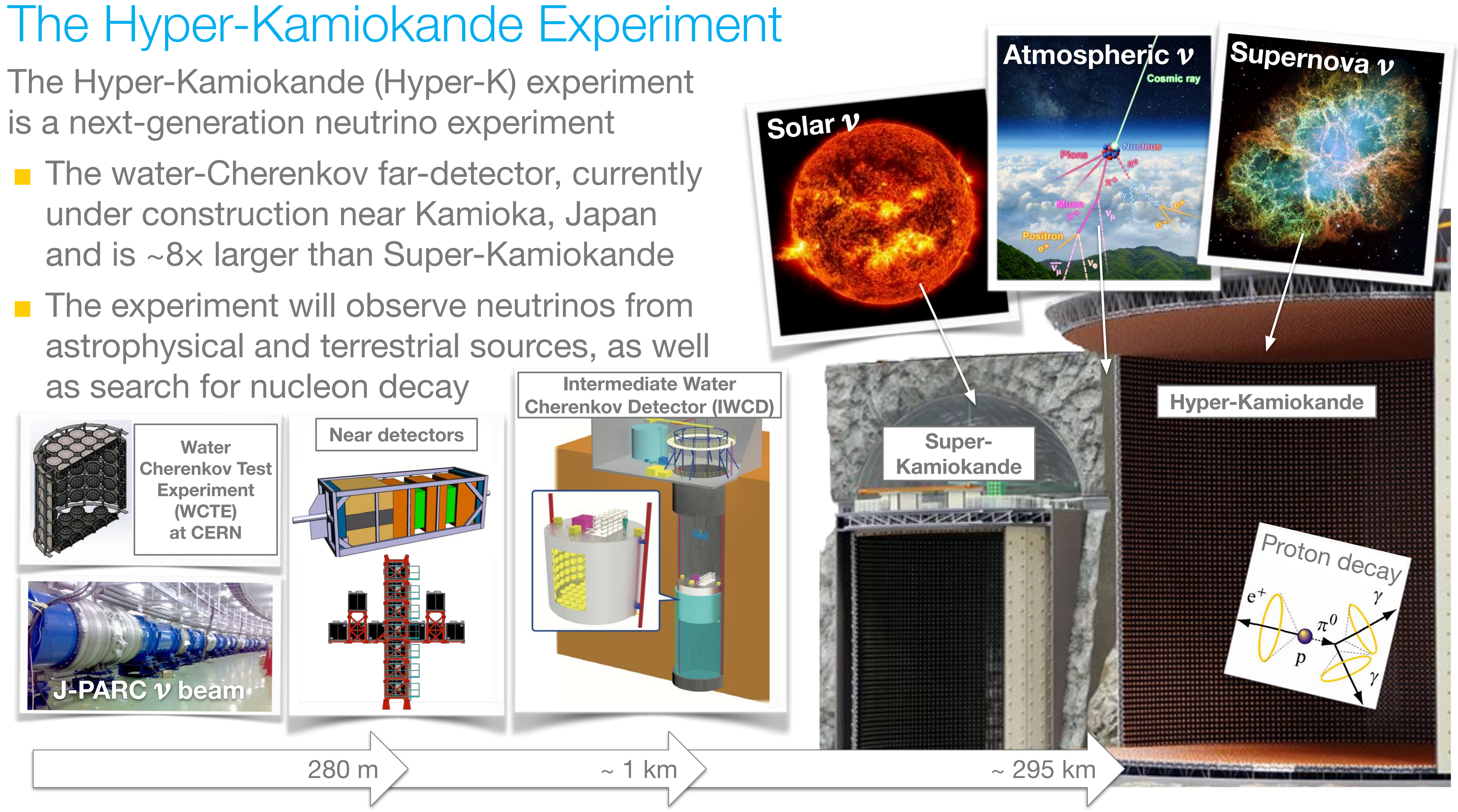
The Hyper-Kamiokande Experiment

The Hyper-Kamiokande (Hyper-K) experiment is a next-generation neutrino experiment

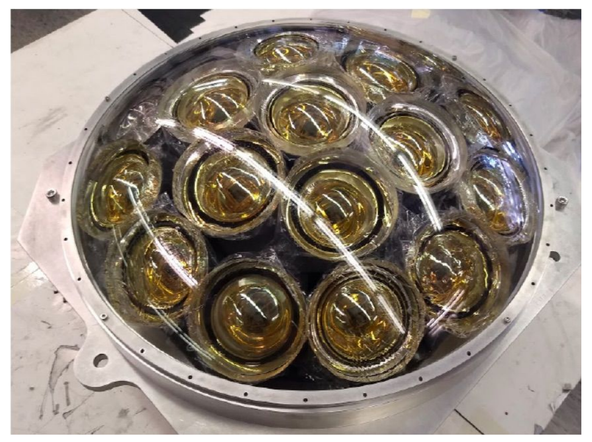
- The water-Cherenkov far-detector, currently under construction near Kamioka, Japan and is ~8x larger than Super-Kamiokande
- The experiment will observe neutrinos from astrophysical and terrestrial sources, as well as search for nucleon decay

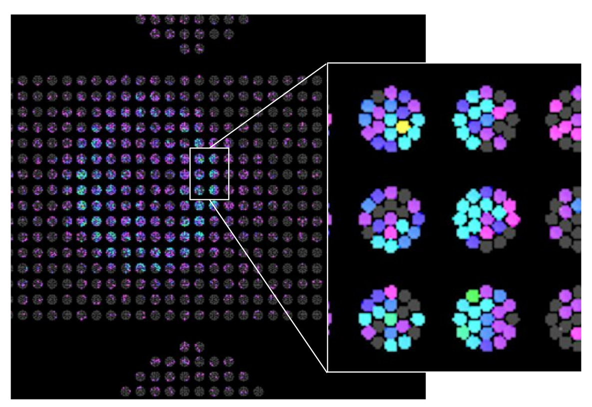


The Intermediate Water Cherenkov Detector

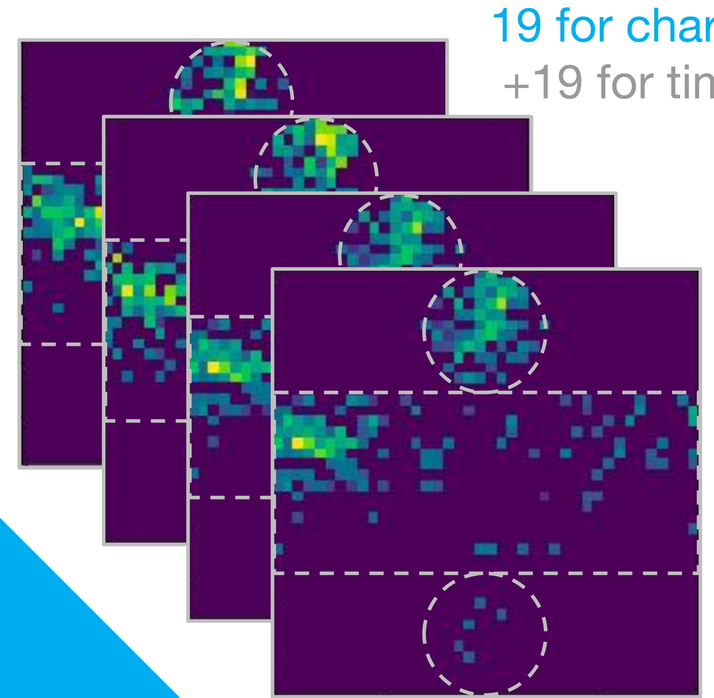
The Intermediate Water Cherenkov Detectors (IWCD) is planned to be built ~ 1 km from the J-PARC neutrino beam, to measure the un-oscillated beam flux and interaction cross-sections

- Development is being led by the TRIUMF and Canadian Hyper-K members, with 5.4M CAD CFI-IF funding for IWCD approved
- The 6m tall, 8m diameter tank is surrounded by ~ 500 multi-PMT modules (mPMTs) around the barrel and two end-caps
- Each mPMT contains 19 individual 8cm PMTs, providing greater position and direction granularity and improved timing resolution
- The detector can move vertically in a ~ 50 m tall pit to measure the beam at different angles providing different ν energy fluxes
- IWCD data consists of the charge and time of hits observed in the 19 PMTs in each mPMT module





19 for charge
+19 for time



Reconstruction in WC Detectors

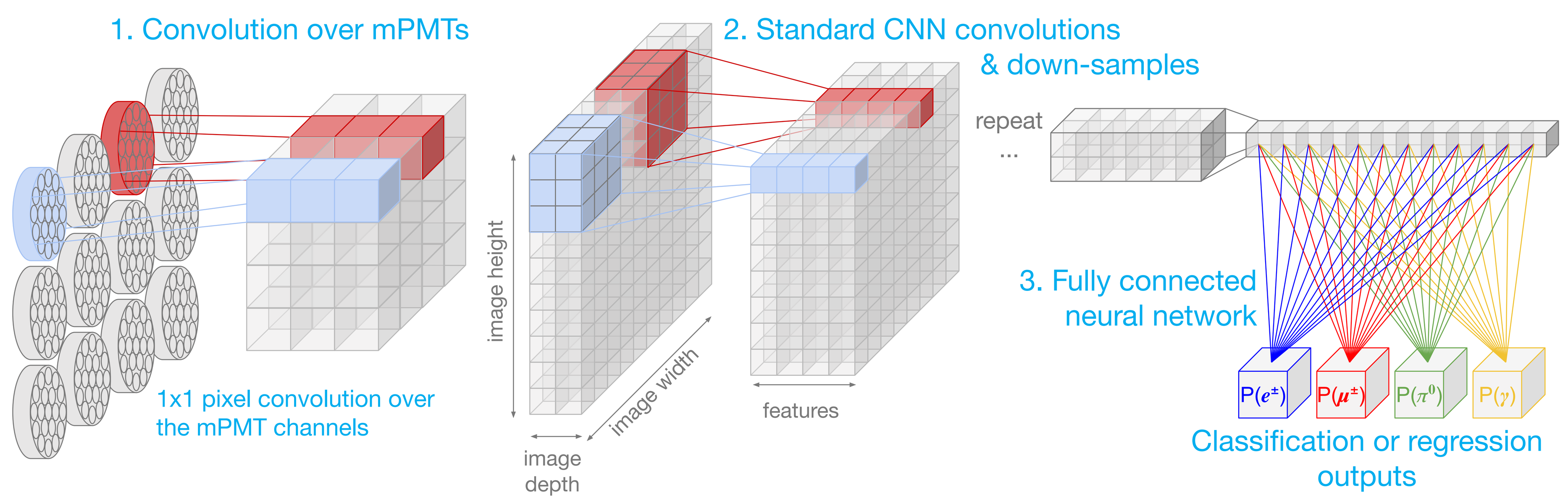
The traditional likelihood method (fiTQun) used for reconstruction in Super-K, Hyper-K and IWCD is reaching the limits of achievable precision

- Hyper-K requires improved reconstruction of particles in complex multi-ring event topologies
- Computation time is a limiting factor in larger detectors or when greater precision requirements need complex models with fewer approximations
- Machine learning (ML) approaches can use all information without physics approximations, in a fraction of the computation time

ResNet CNN Architecture

The ResNet architecture has been adapted to apply to geometry of the IWCD by unwrapping the cylindrical geometry into a 2D image.

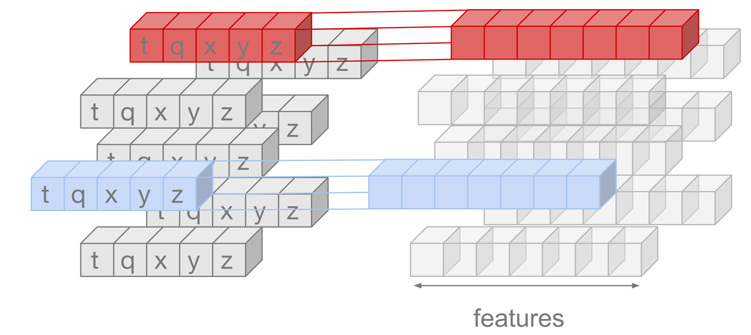
- To minimise effects due to the choice of slice along the side of the tank's barrel when unrolling, the image contains a double-cover of the detector surface, duplicating the data from two different viewpoints.
- After an initial 1×1 convolution over the channels (PMTs) of the multi-PMT modules, standard CNN operations are performed with residual connections following the ResNet-18 architecture.
- Data augmentation is applied by reflecting the tank about the 3D axes.



PointNet Architecture

The PointNet architecture acts on a point cloud instead of a 2D image, using the full 3D detector geometry.

- Each point is a PMT hit with charge, time and position.
- The majority of layers involve 1×1 convolutions on points (PMTs)
- Information passes between points by applying arbitrary learned transformations
- A single downsample leads to the fully connected network

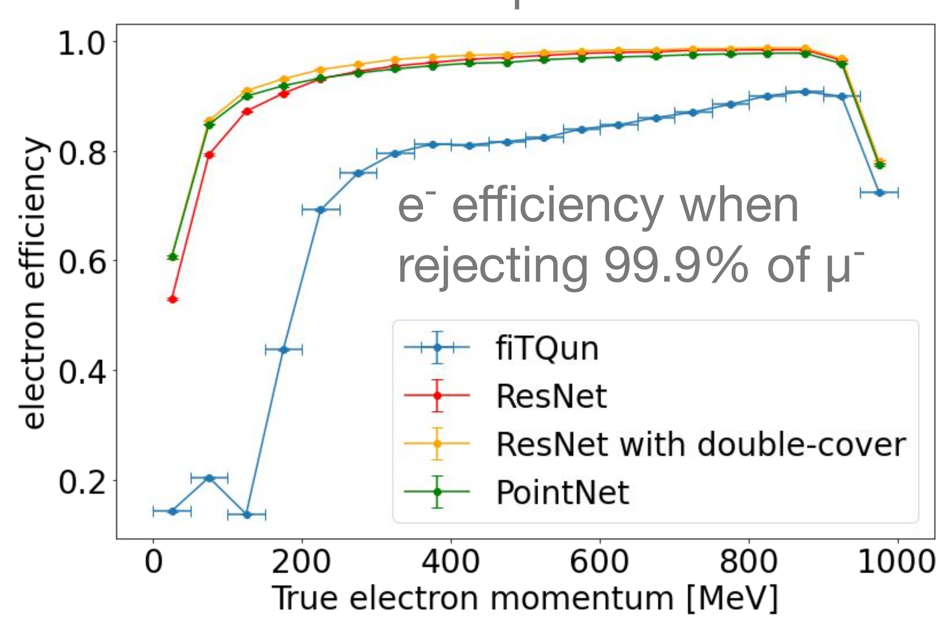


PointNet layer (1×1 convolution on point cloud)

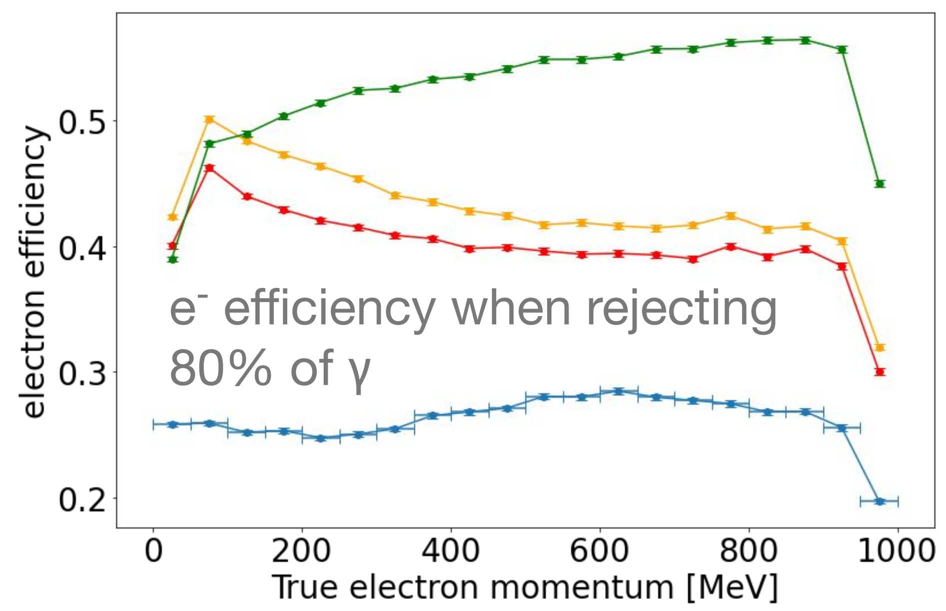
Classification

Particle identification with ML significantly outperforms fiTQun.

- ResNet performs slightly better than PointNet for e^- vs μ^- classification

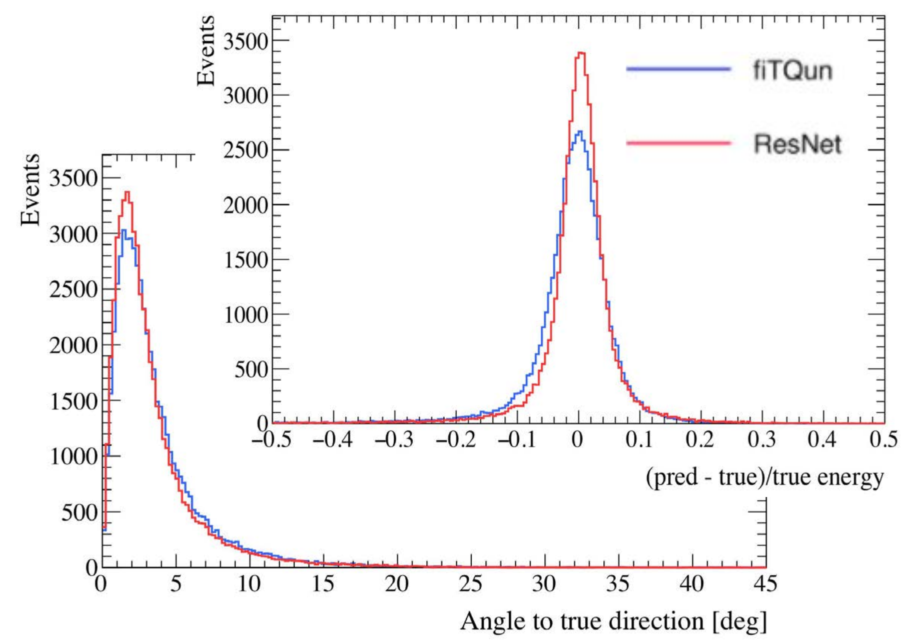


- PointNet performs better than ResNet for e^- vs γ classification

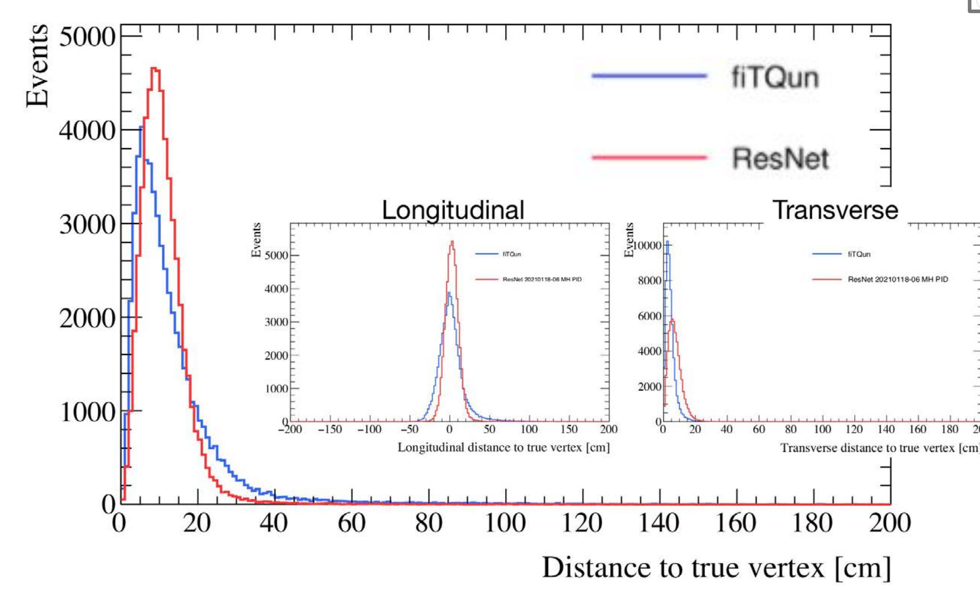


Regression

- Reconstructing energy and direction with ResNet outperforms fiTQun

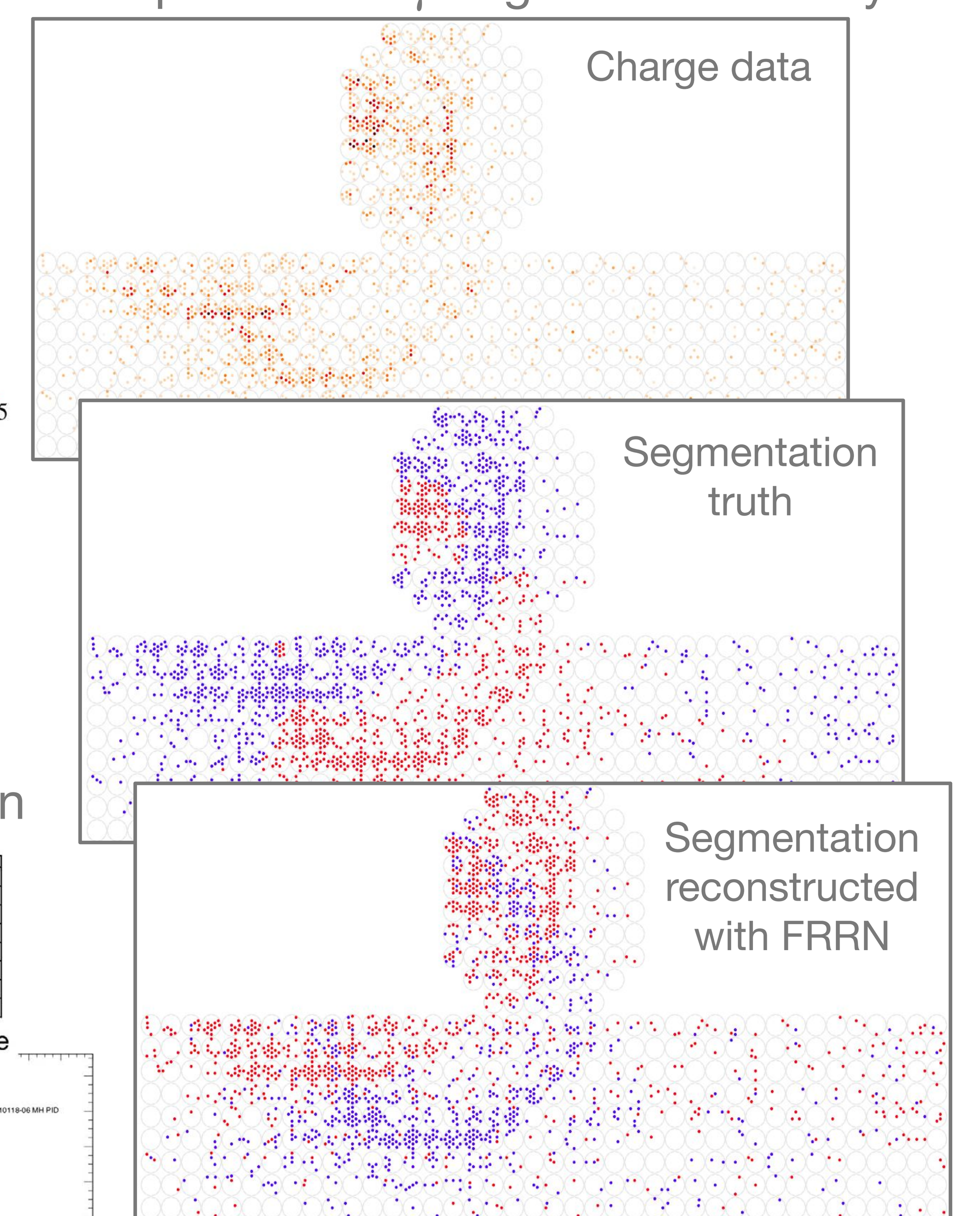


- ResNet position reconstruction improved in particle direction but underperforms in transverse direction



Segmentation

- CNN architecture adapted to segment image into rings, trained to separate two γ rings from π^0 decay.



Discovery, accelerated