

QVAE w/ Pegasus

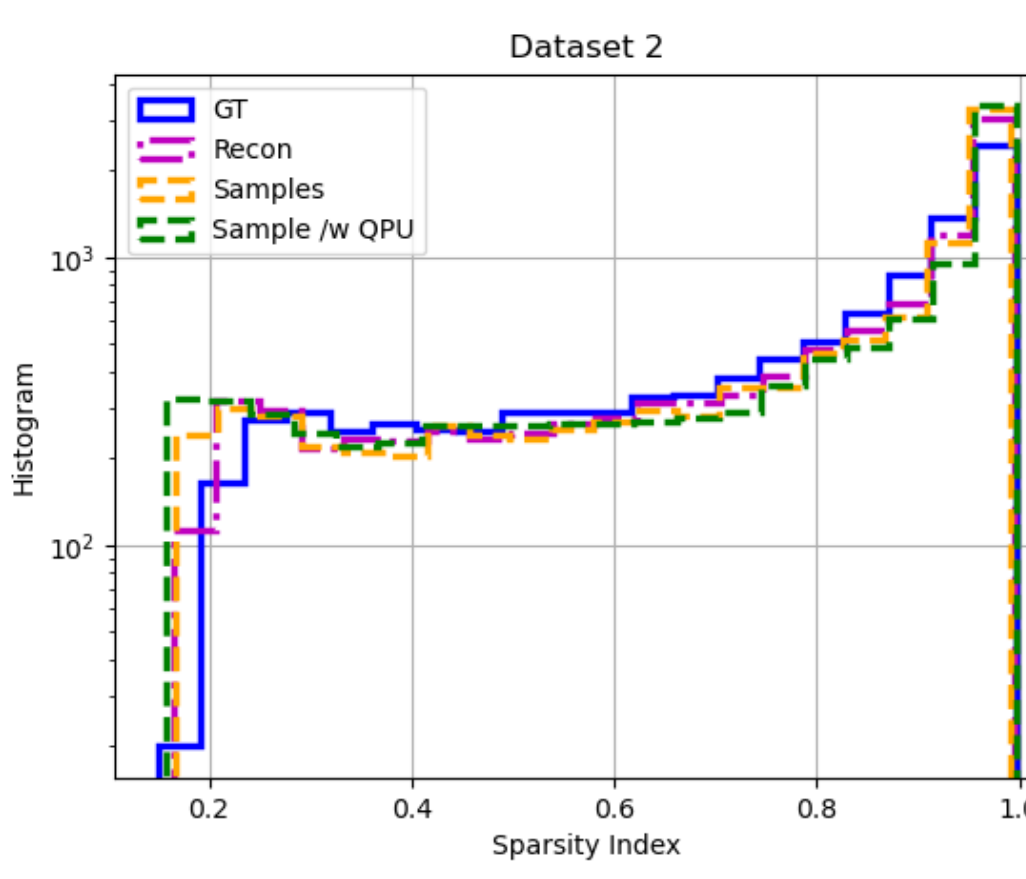
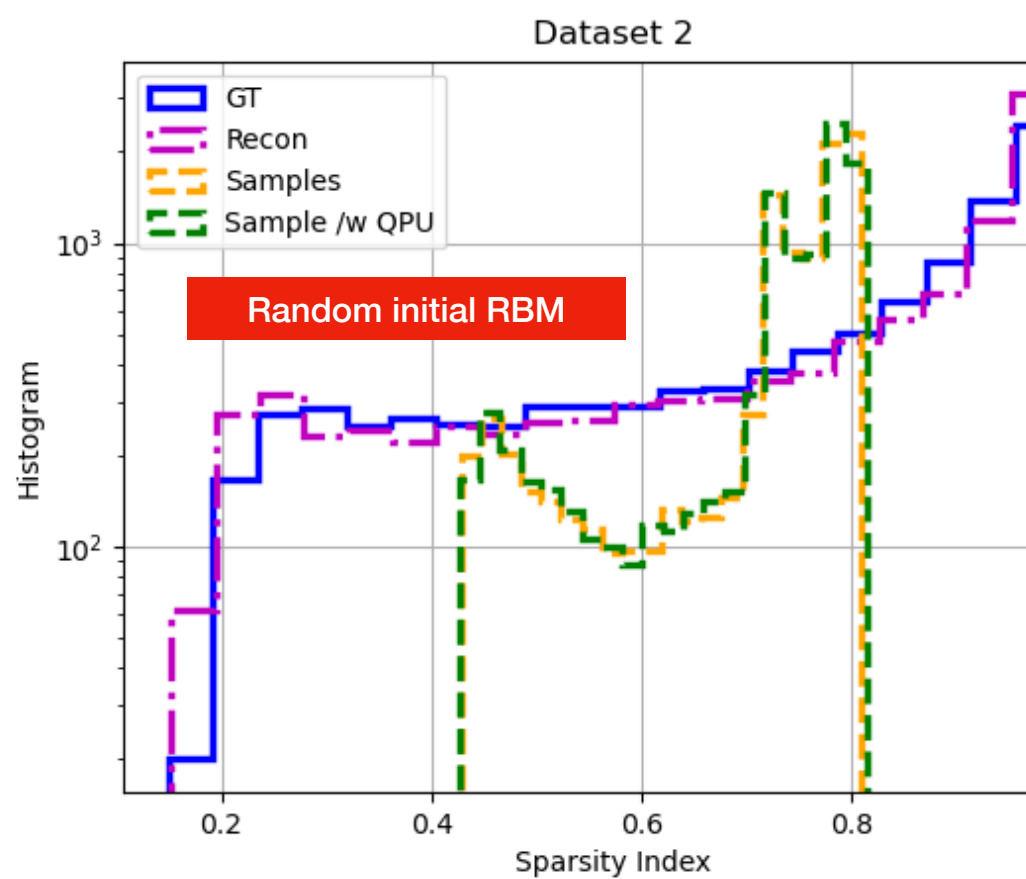
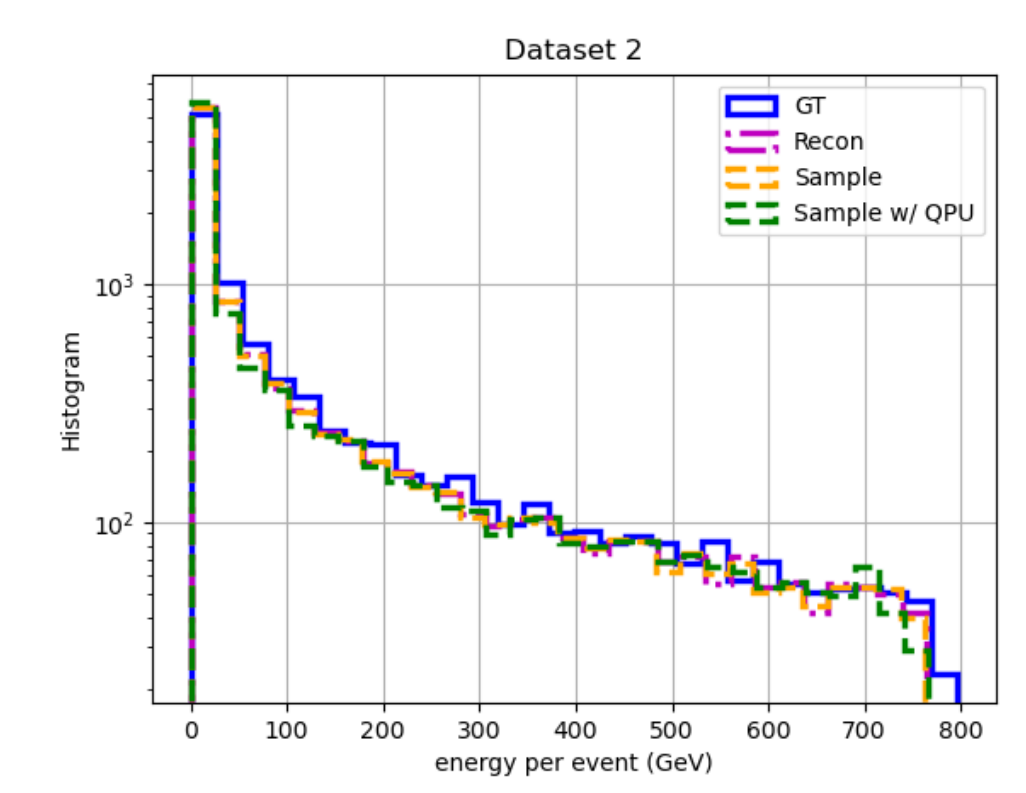
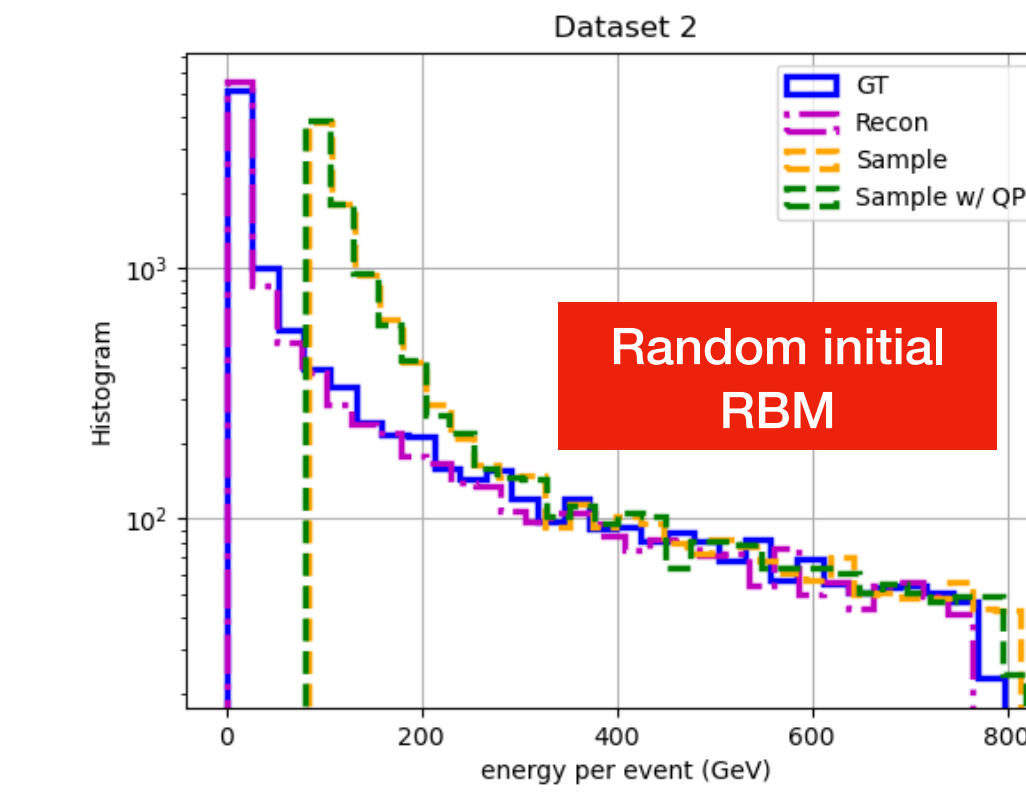
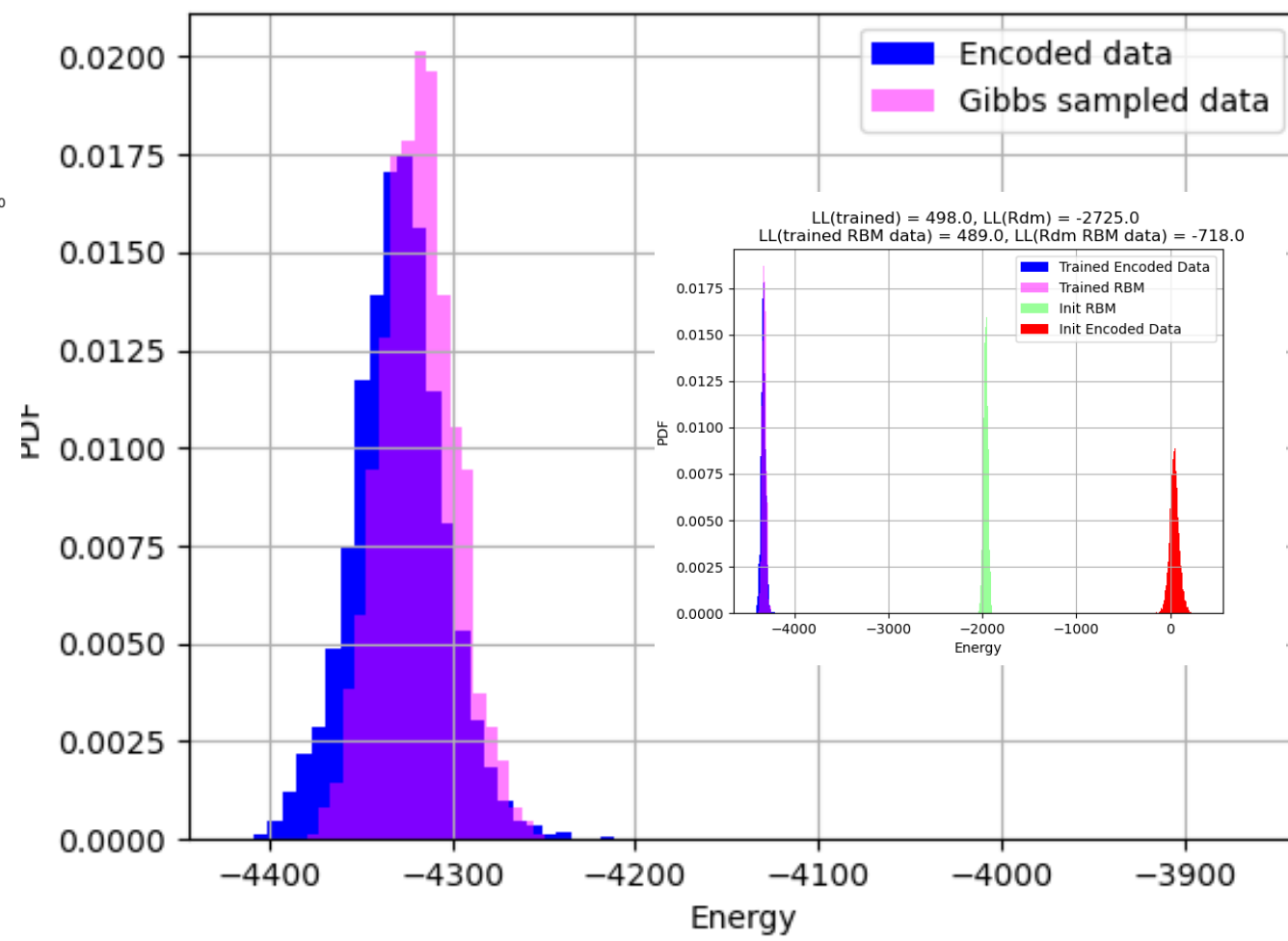
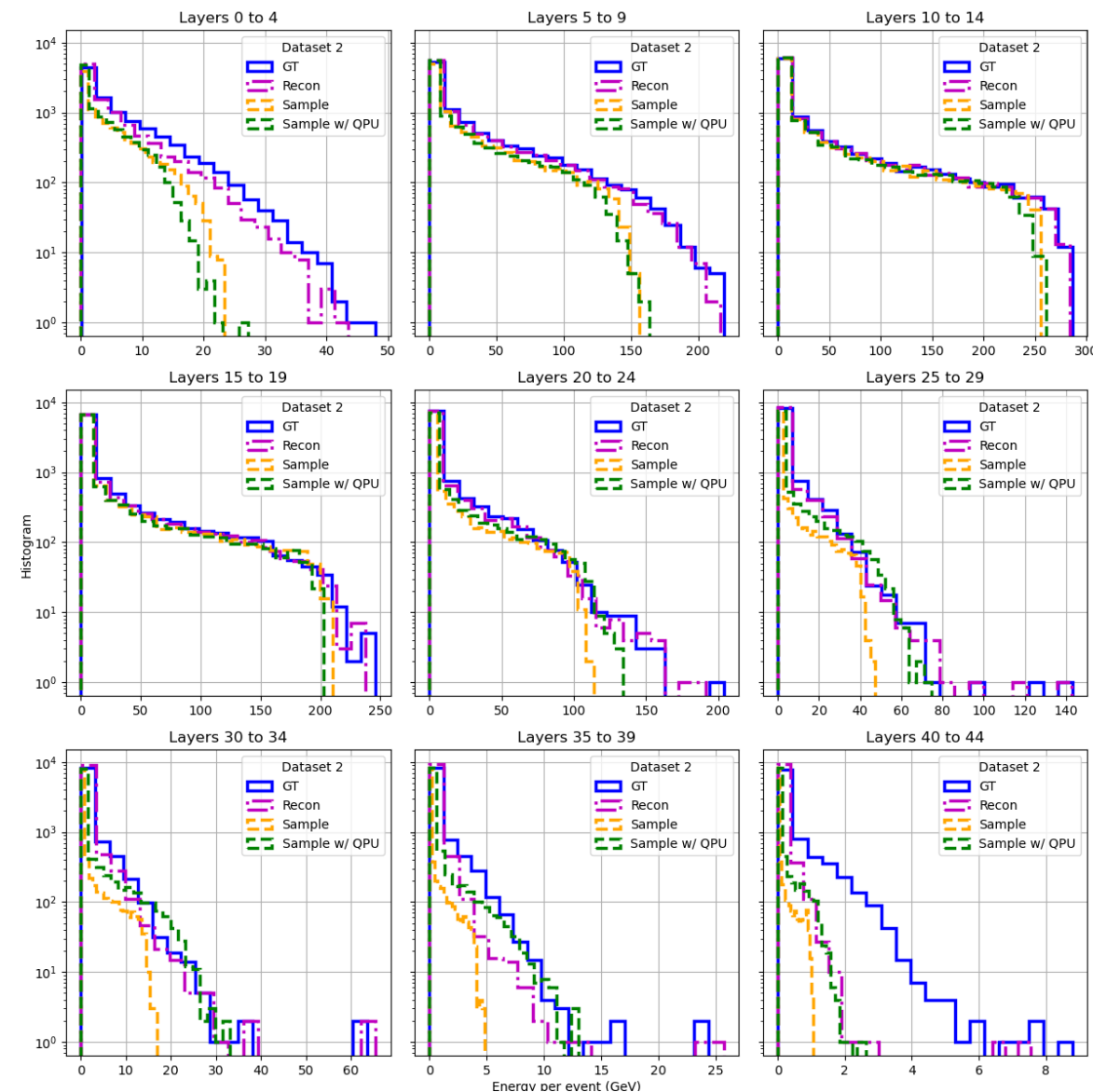
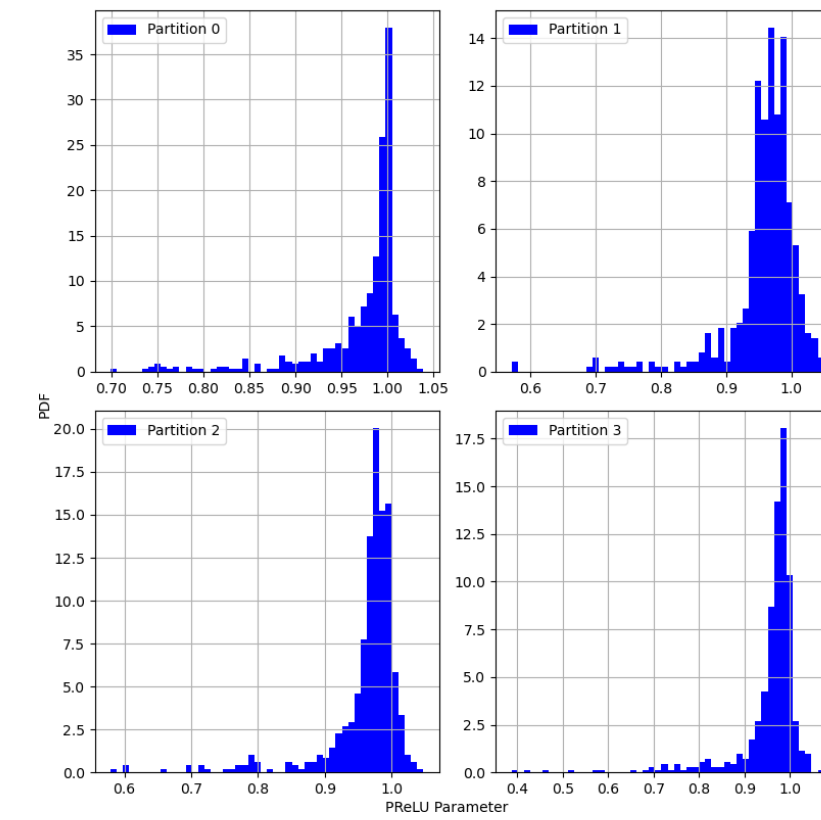
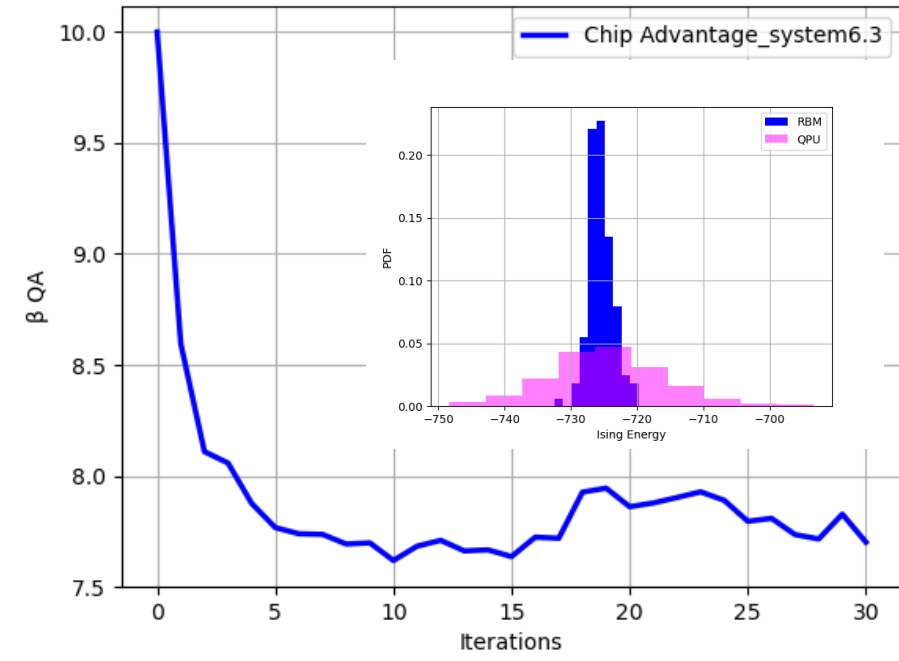
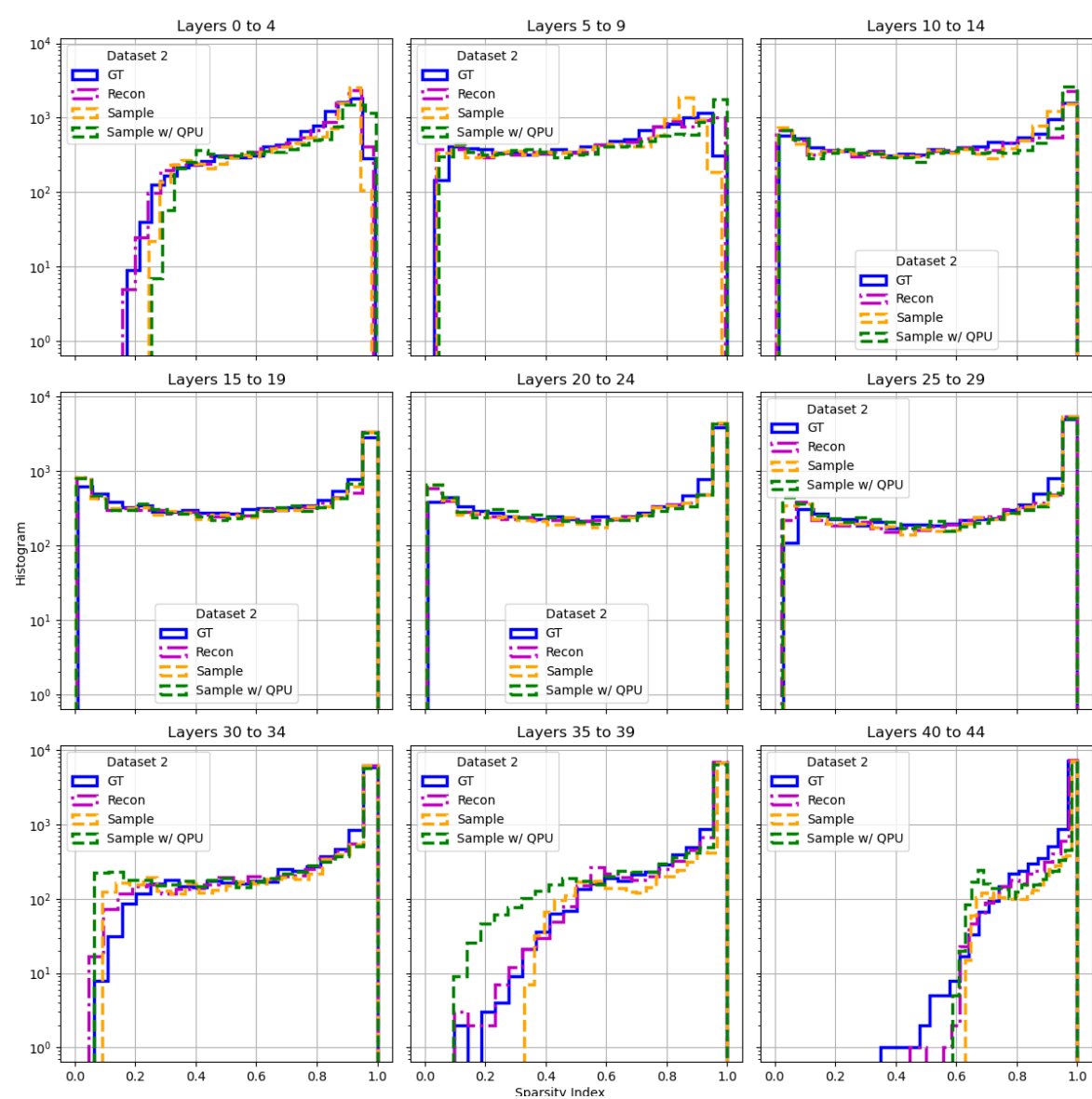
Dec 1st

- QVAE
 - Architectures
 - CNN
 - FCN
 - Energy incidence
 - Condition on encoder and decoder
 - Condition on encoder
 - Unconditionalized
 - Modulated energy => Can lead to learning how to modulate more features, position of voxels, angles, etc.
 - Results/metrics
 - Energy histogram
 - Sparsity histogram
 - Conditionalized energy and sparsity histogram (NOT GOOD)
- RBM
 - Topology
 - Chimera-like
 - Pegasus
 - Metrics
 - Energy distribution for encoded and RBM Gibbs samples
 - Zais and Zrais estimates for partition function => log-likelihood of model
 - Dwave
 - Sehmi's method
 - Fast stein. Not robust but could be helpful?
 - Hao's method
- Theory. Work in progress

- In the previous slides (Nov 18th), model super-valley-246 seem to check every aspect decently well (RBM energy overlap between encoded data and Gibb samples, good recon, good samples, robust RBM).
- Here we tried conditioning the energy by ***positional embedding***. Basically, instead of concatenating the “incident energy”, we simply add it to the torch tensor in the encoder and the decoder.
- We also tried the ***positional encoding*** of the voxels by adapting the positional encoding done in transformers for LLM. In LLM we have 1D vectors, but in our case, we have a cylinder, so we applied positional encoding *a la Attention is all you need* in (r, ϕ, z) .
- For the latter model, there were some instabilities during training. So the results are not conclusive.

super-valley-246

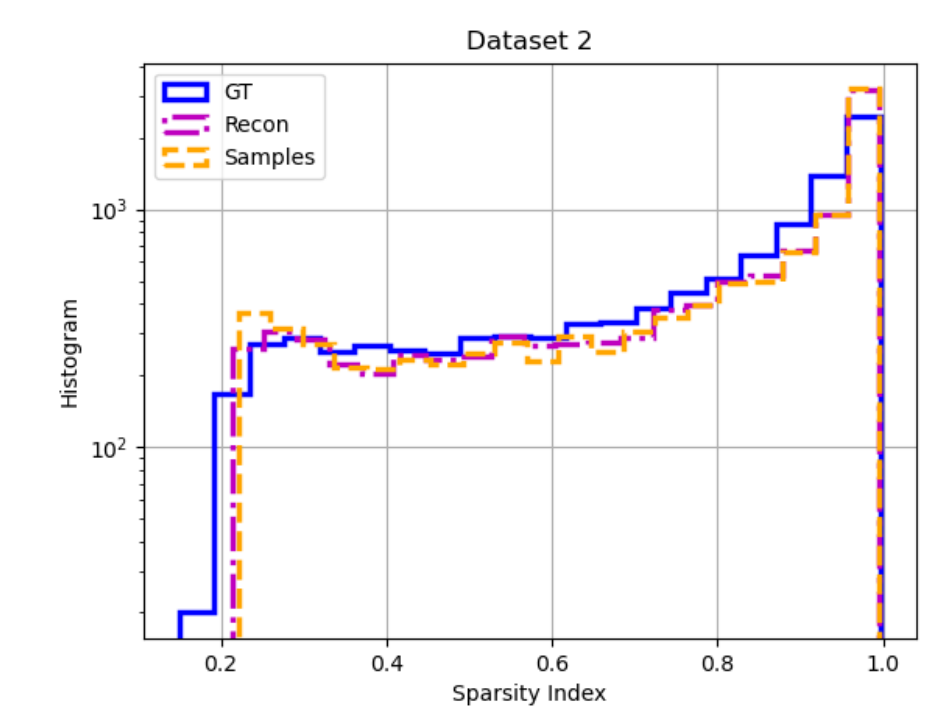
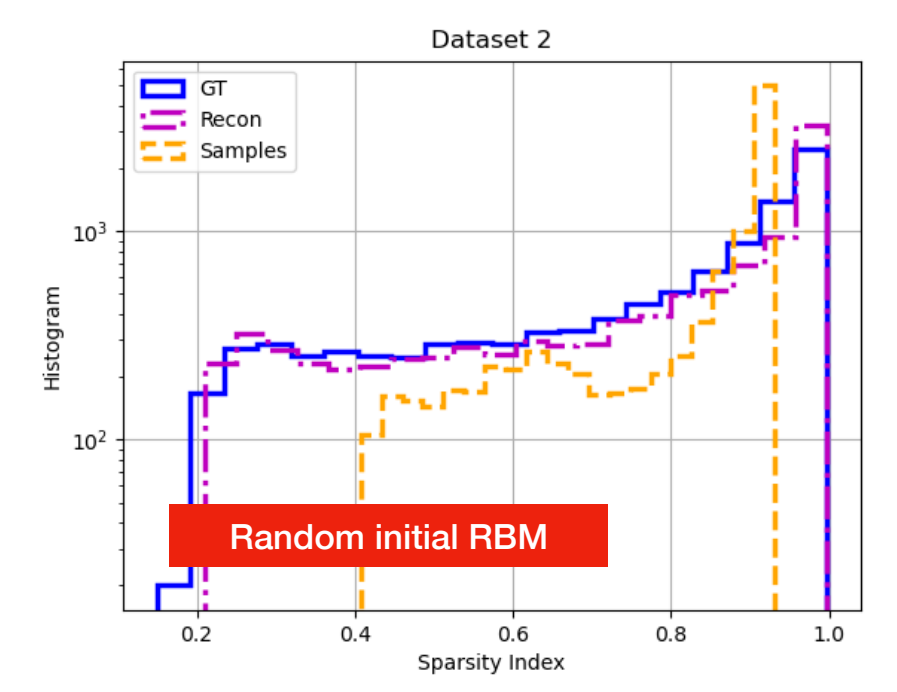
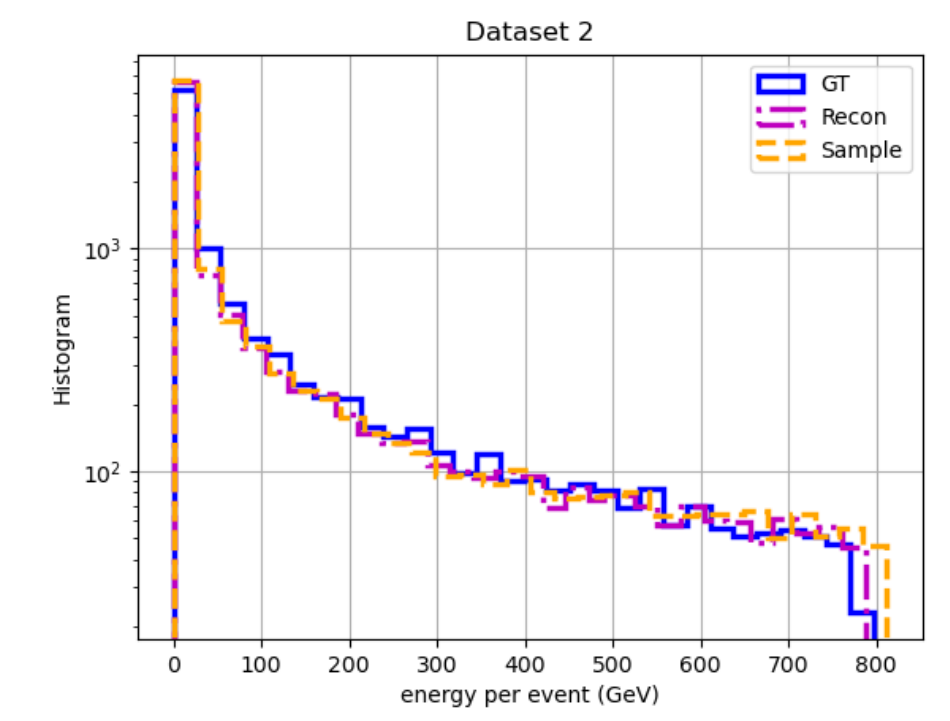
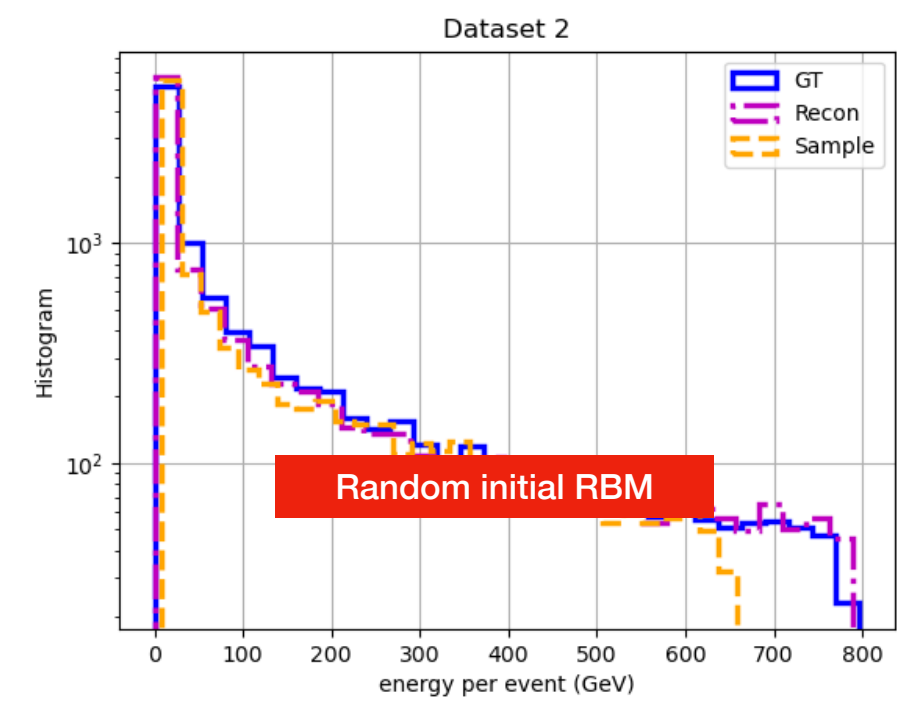
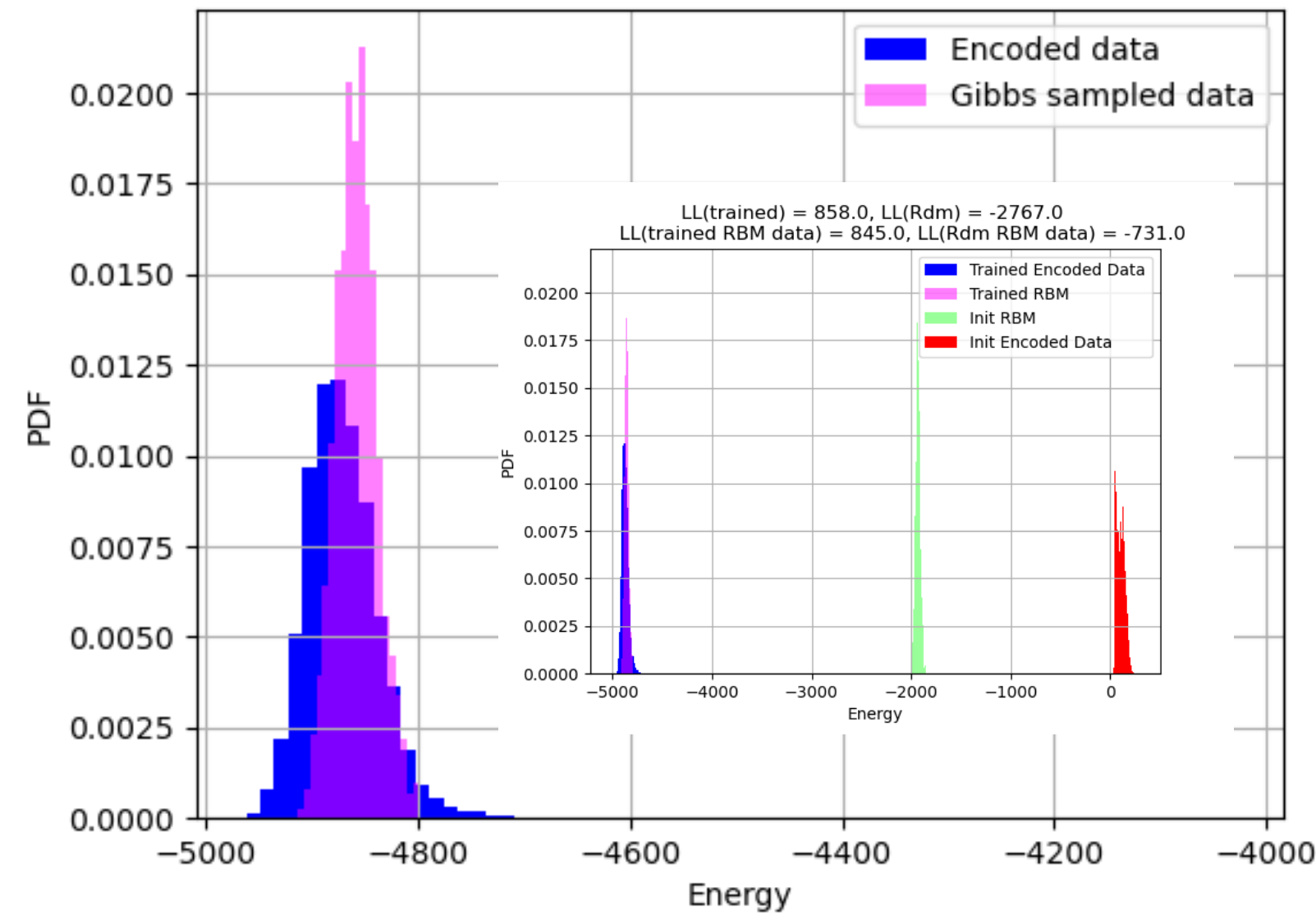
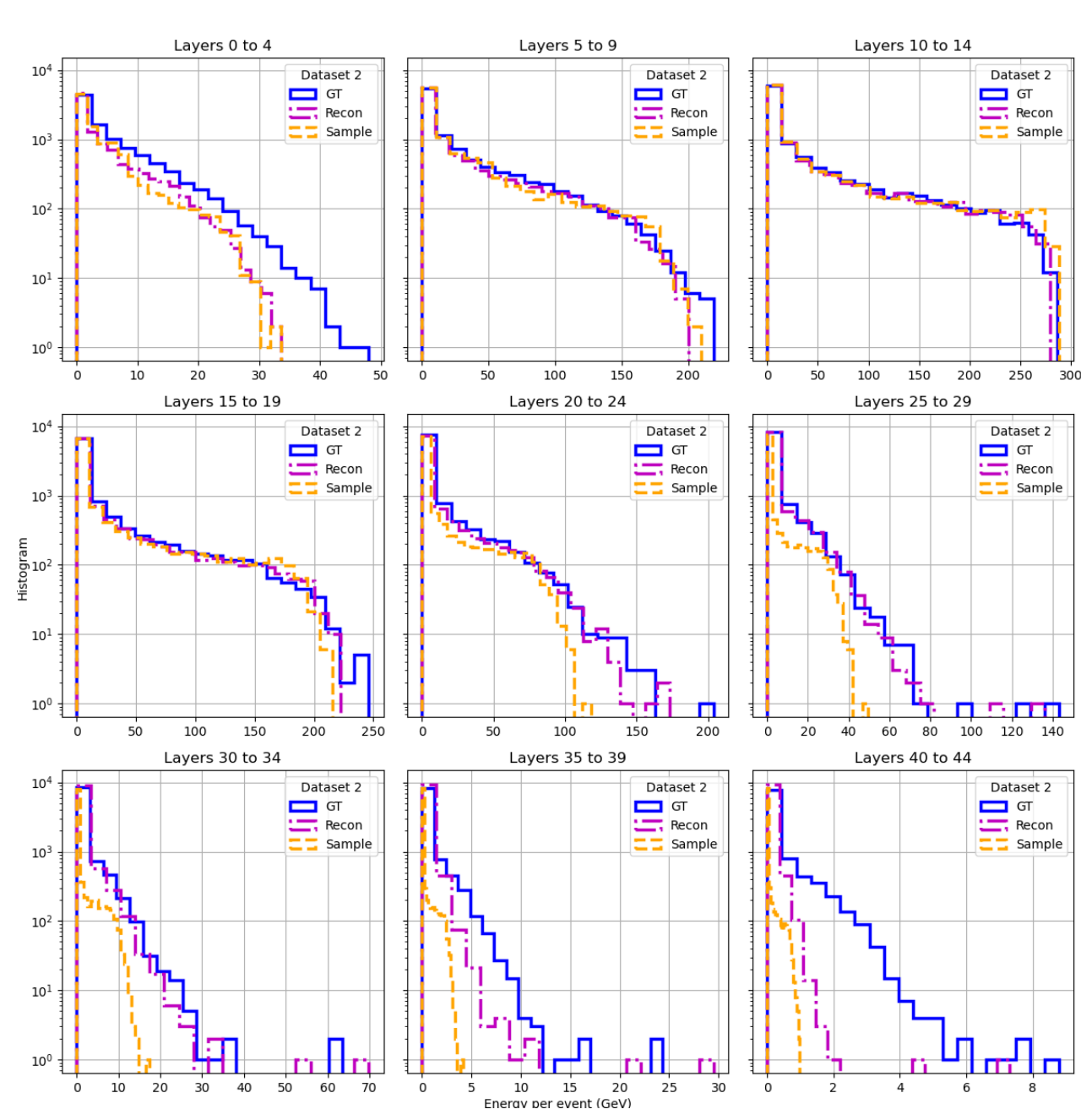
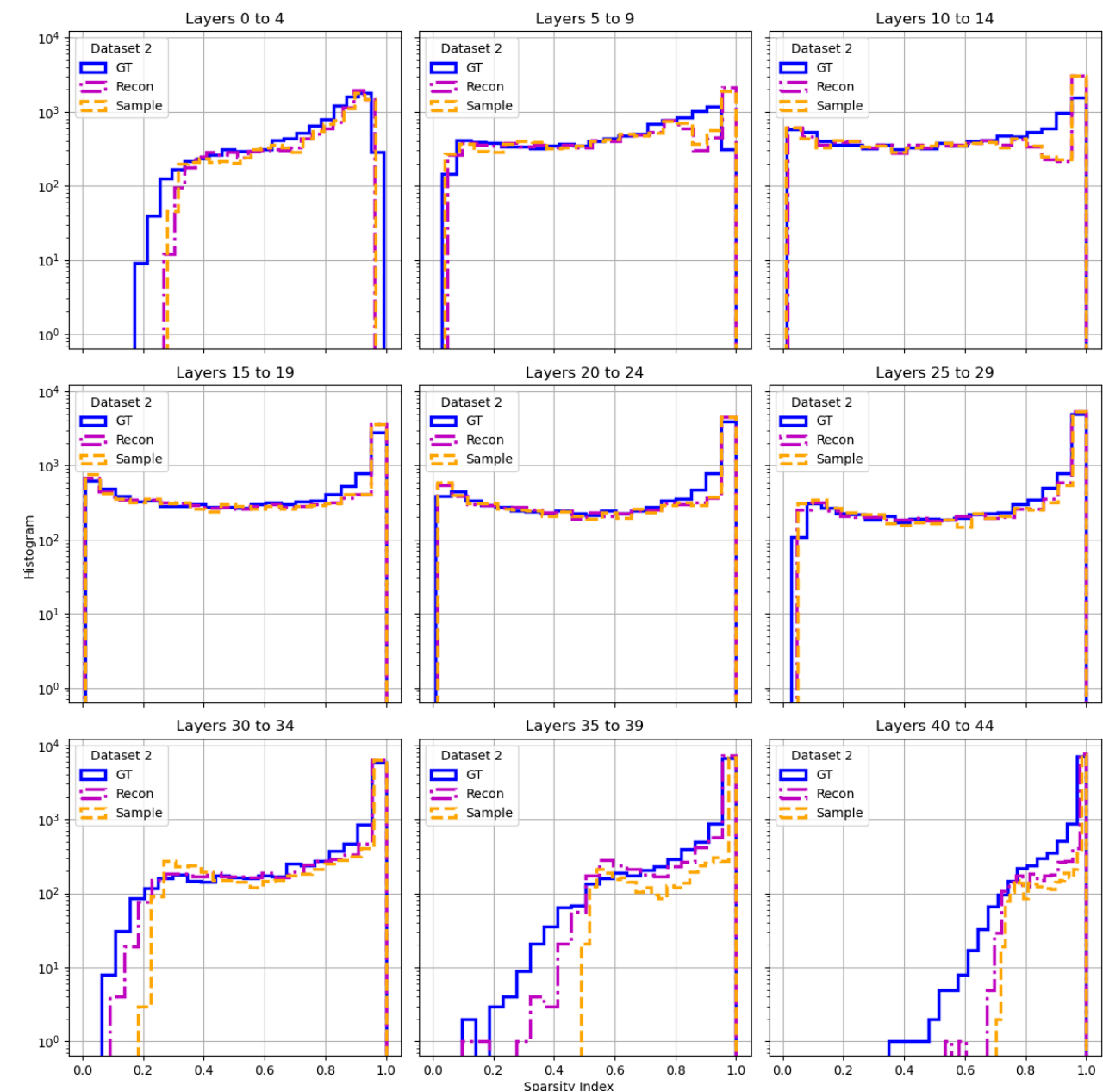
CNN + fully conditioned+scaled data



LL(Trained) = Trained model Log-likelihood evaluated on the encoded validation dataset.
 LL(Trained RBM data) = Trained model Log-likelihood evaluated on Gibbs sampled data.
 LL(Rdm) = Random RBM model Log-likelihood evaluated on the encoded validation dataset.
 LL(Rdm RBM data) = Random RBM model Log-likelihood evaluated on on Gibbs sampled data.
 We expect $LL(\text{trained}) \sim LL(\text{trained RBM data}) > LL(\text{Rdm RBM data}) > LL(\text{Rdm})$

confused- sponge-256

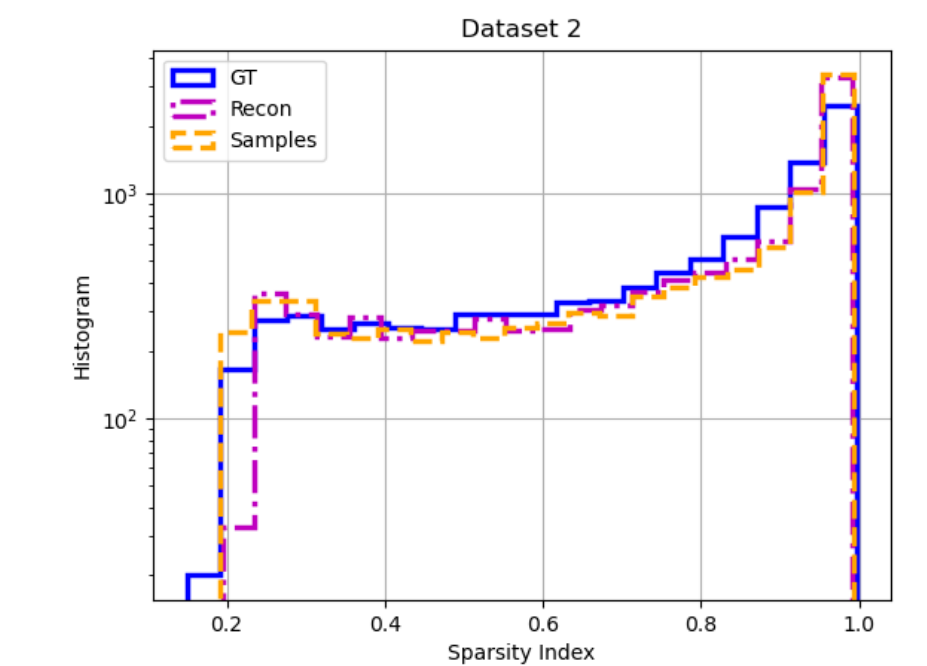
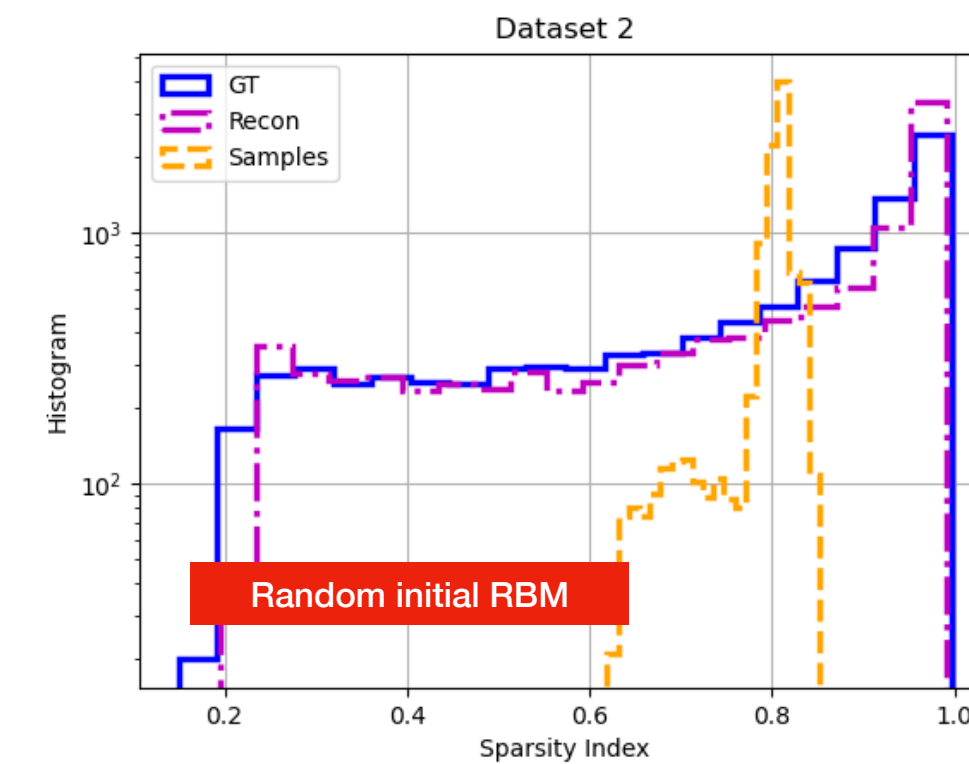
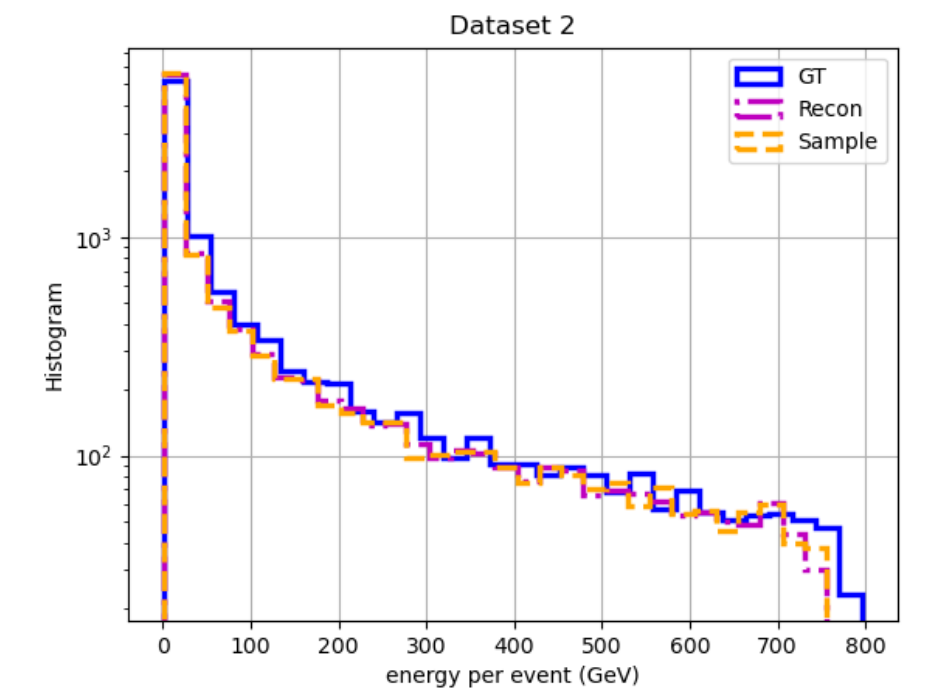
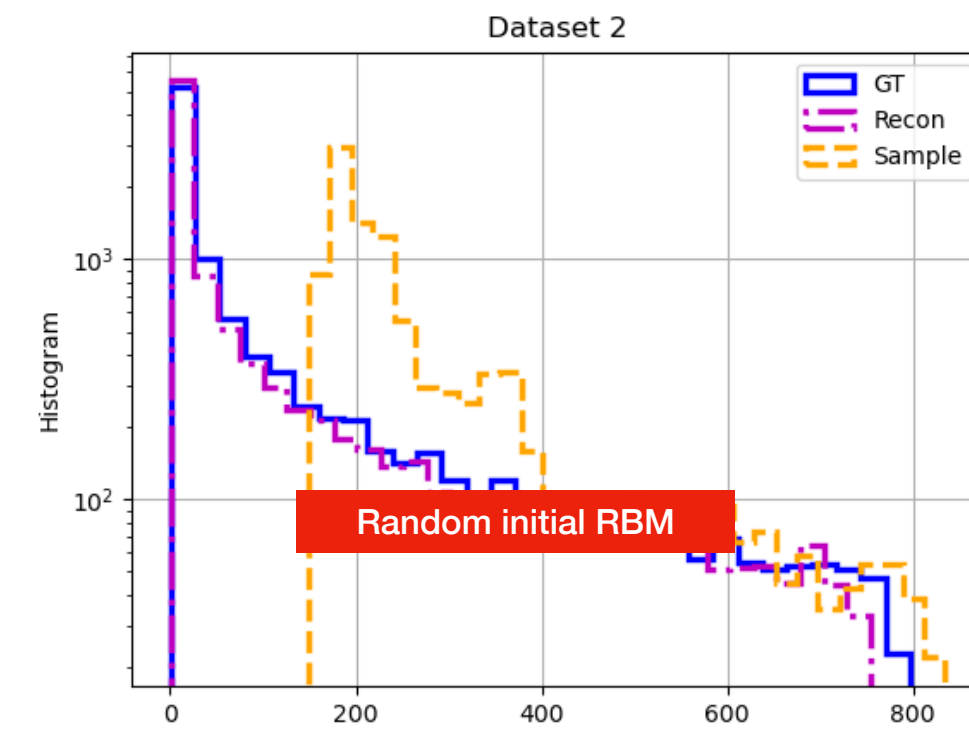
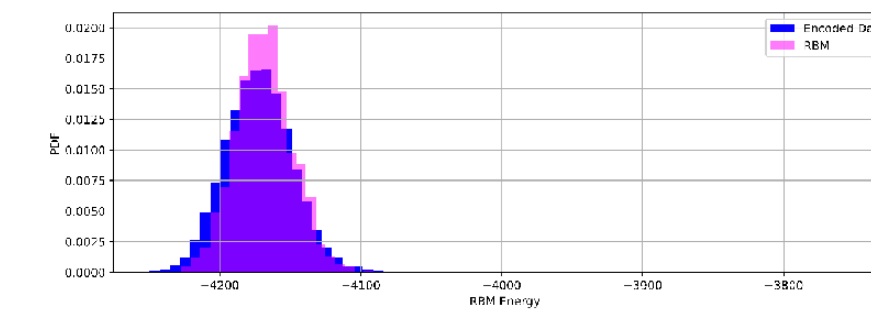
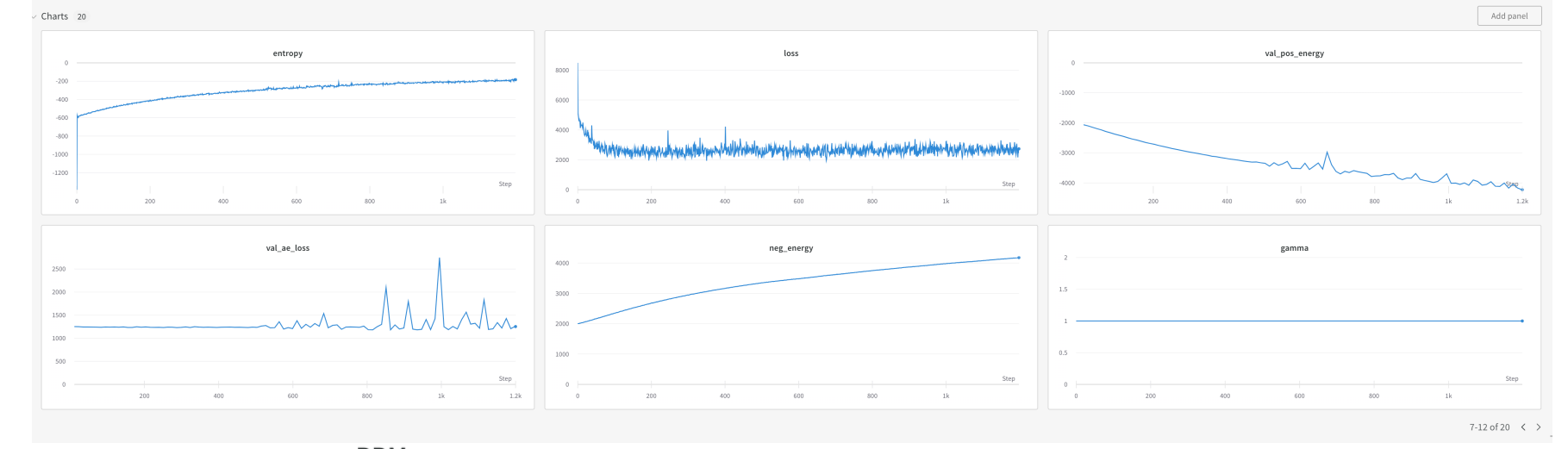
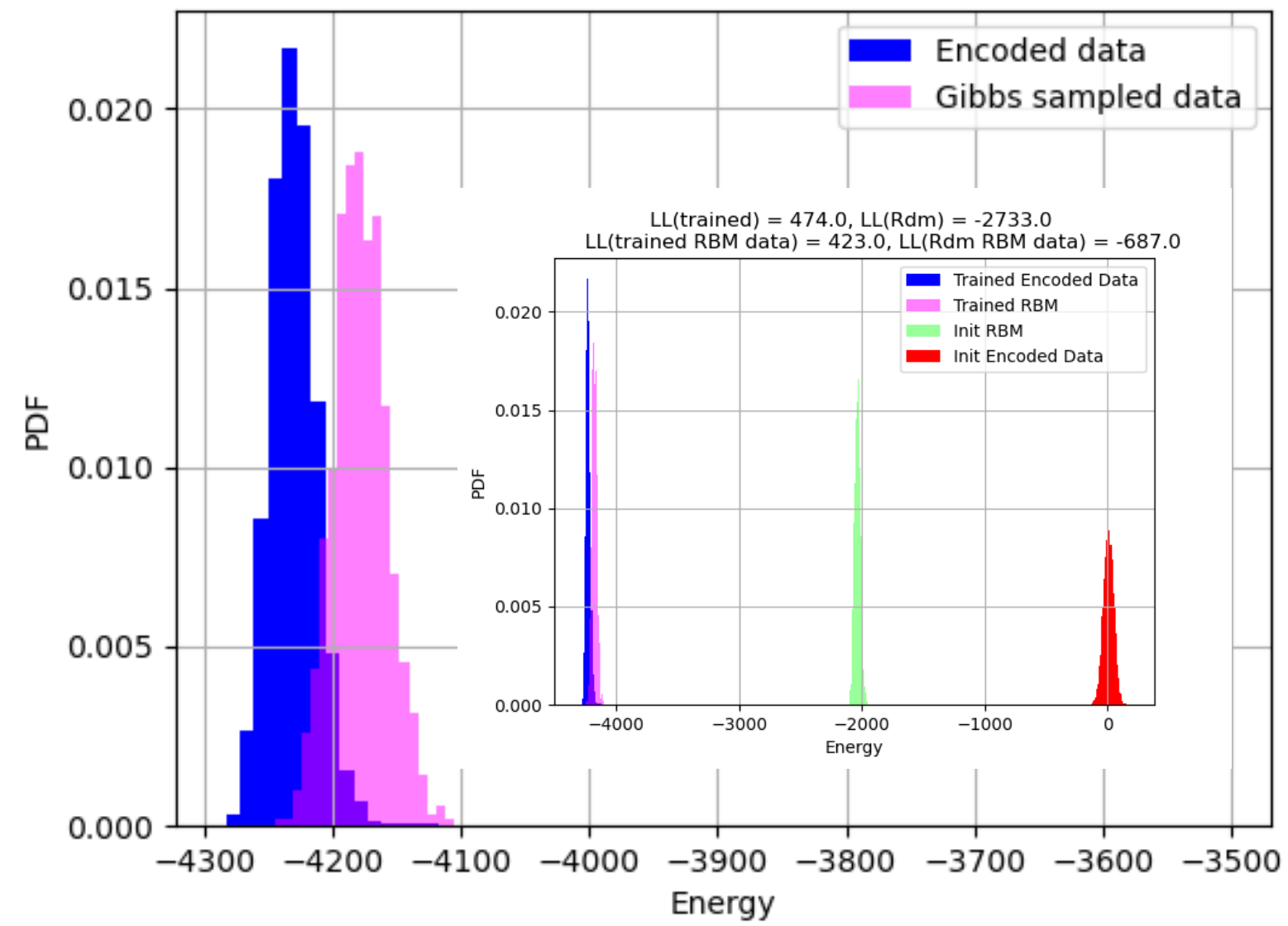
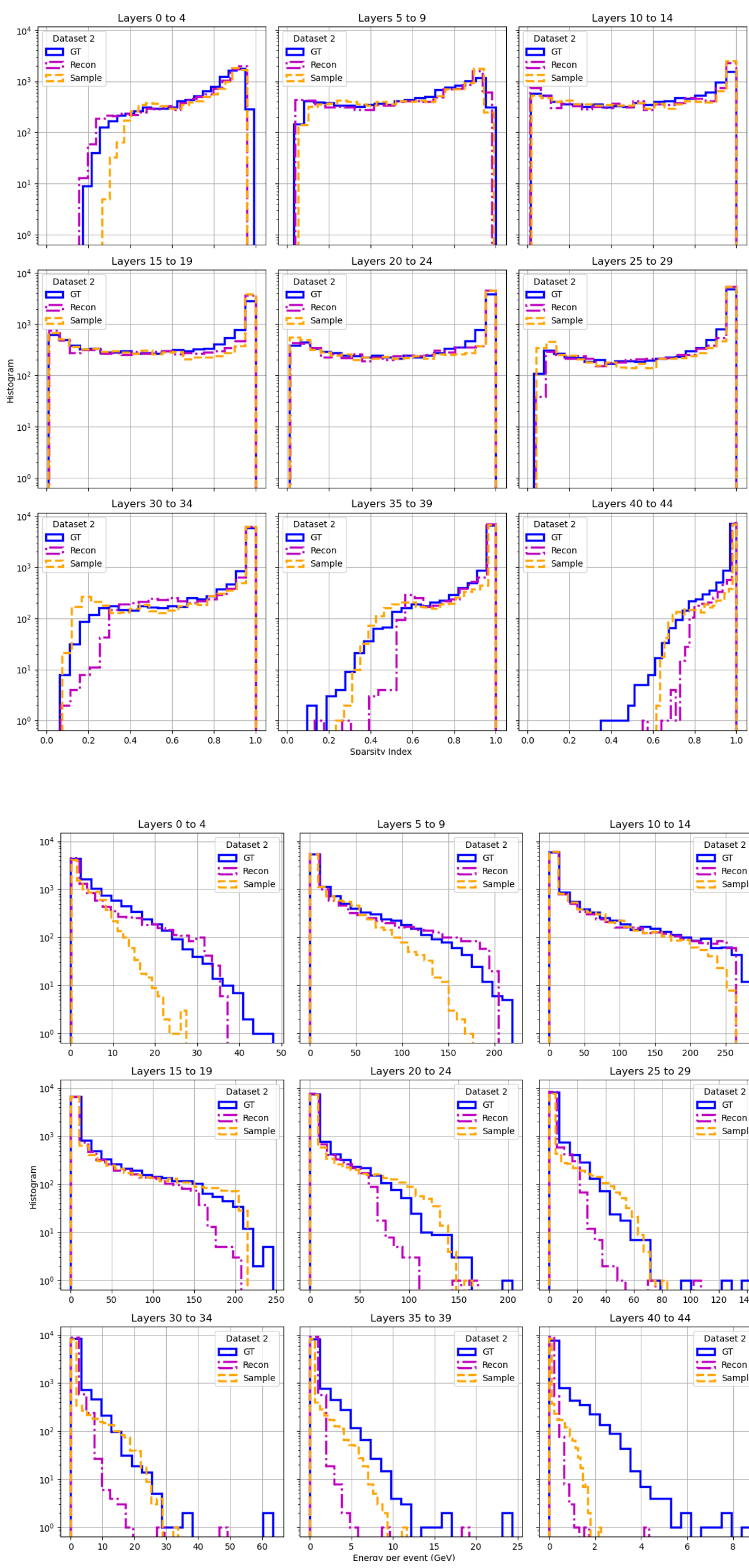
CNN+posEnc cond VAE+scaled data

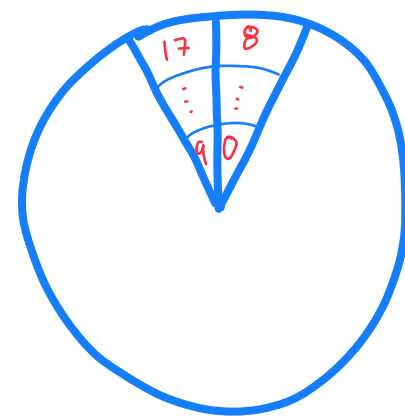
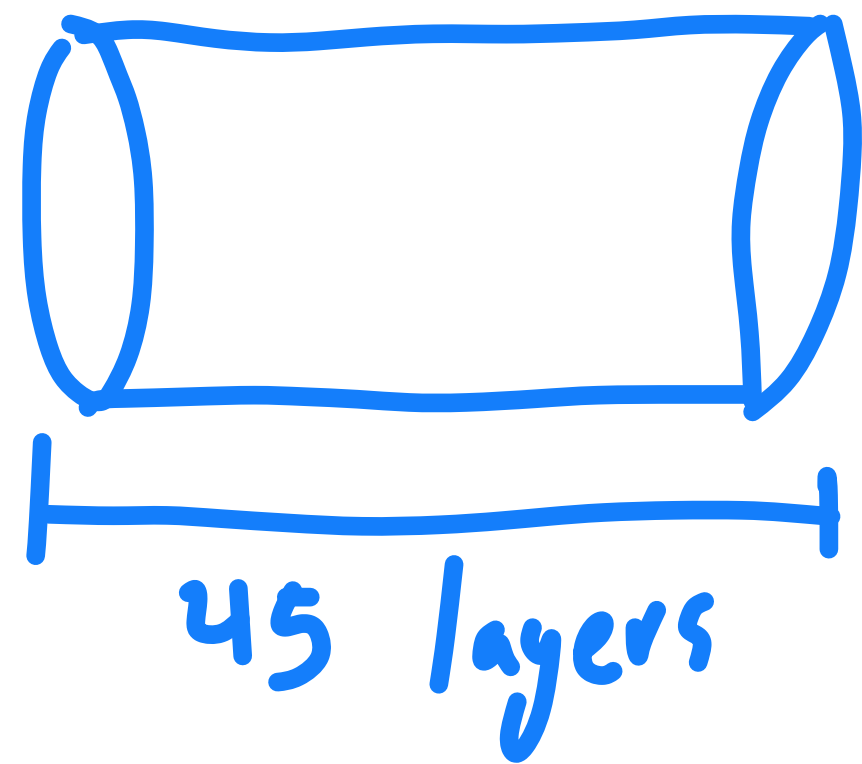


zany-cloud-260

CNN+ cond VAE+posEnc on voxels+scaled data

Somewhat unstable model



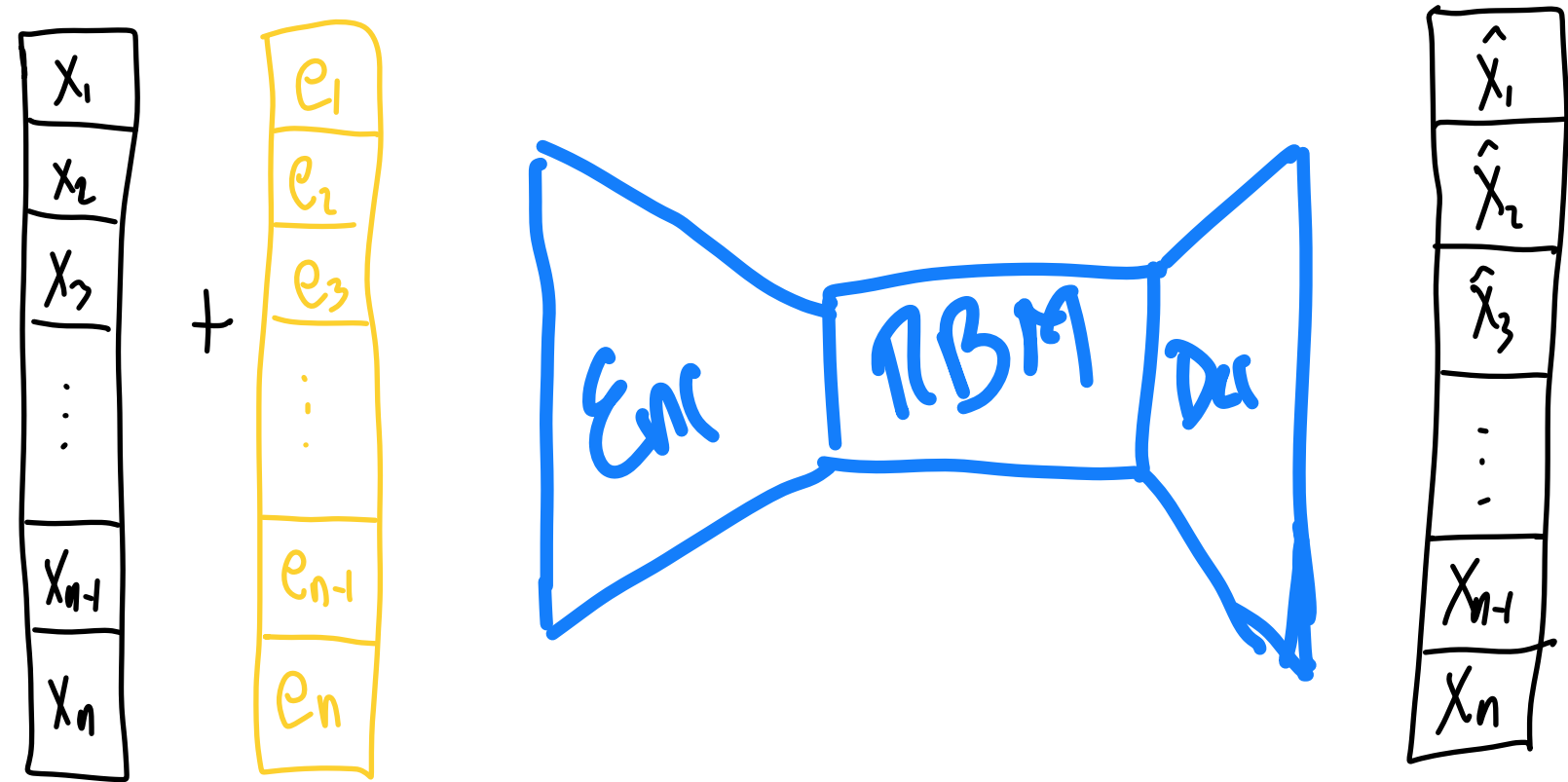


0	1	...	8	9	...	6480
z	0	0	...	0	0	44
r	0	1	...	8	0	8
φ	0	0	...	0	1	15

⇓

$$\boxed{i} \rightarrow \begin{cases} z = i // 144 \\ \varphi = (i - 144 \cdot z) // 9 \\ r = (i - 144 \cdot z) \% 9 \end{cases}$$

Positional encoding



How to obtain e_u ?

$$PE(u, i) = \begin{cases} \text{Sine } K_i u & \text{if } i \text{ is even} \\ \text{Cos } K_i u & \text{if } i \text{ is odd} \end{cases} \quad w/ \quad i = 0, \dots, d$$

$$K_i = 10^{-4} i / d$$

$$\Downarrow$$

$$\lambda_i \in [2\pi, 2\pi \cdot 10^4)$$

$$e_u = \sum_i PE(u, i)$$

$w \sim K$
 $w \in [w_{min}, w_{max}]$
 $\sim \text{Debye}$

zany-cloud-260

CNN+ cond
VAE+posEnc on
voxels+scaled data

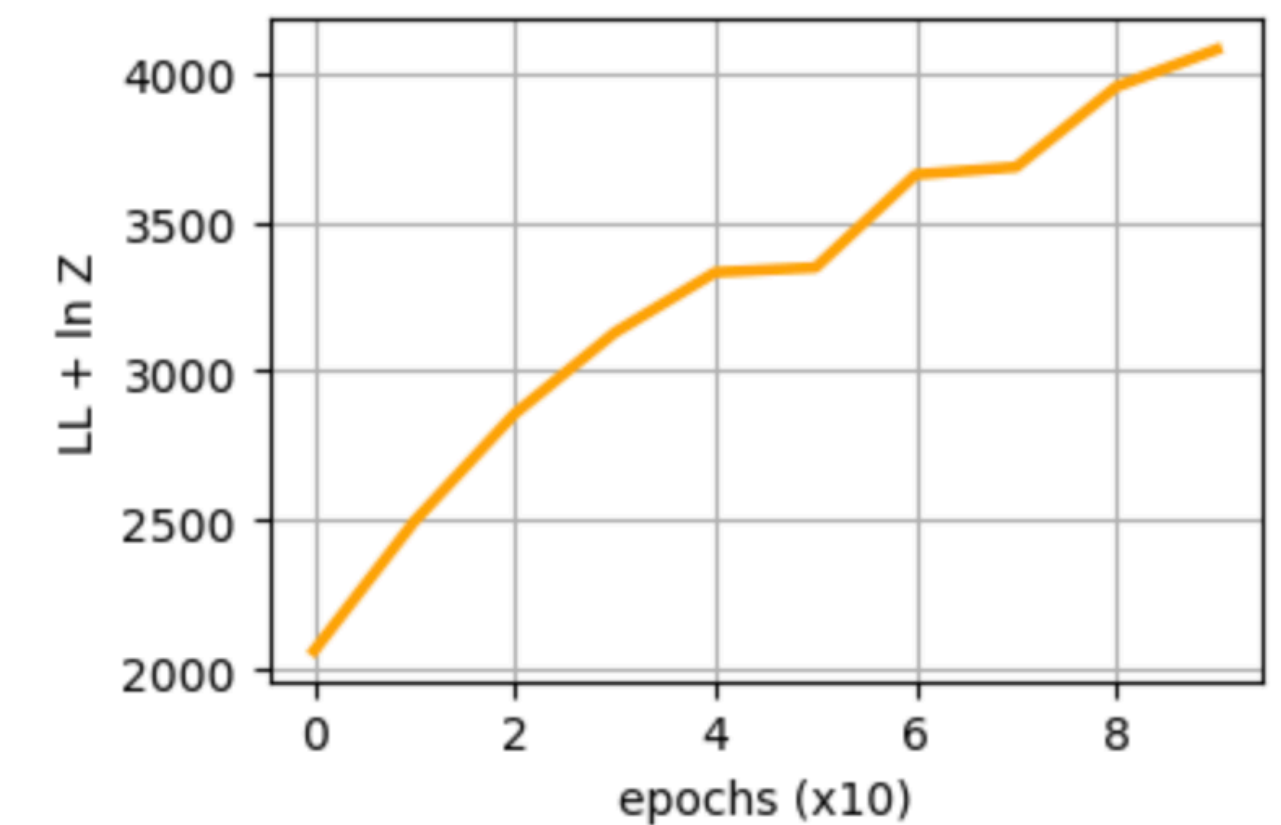
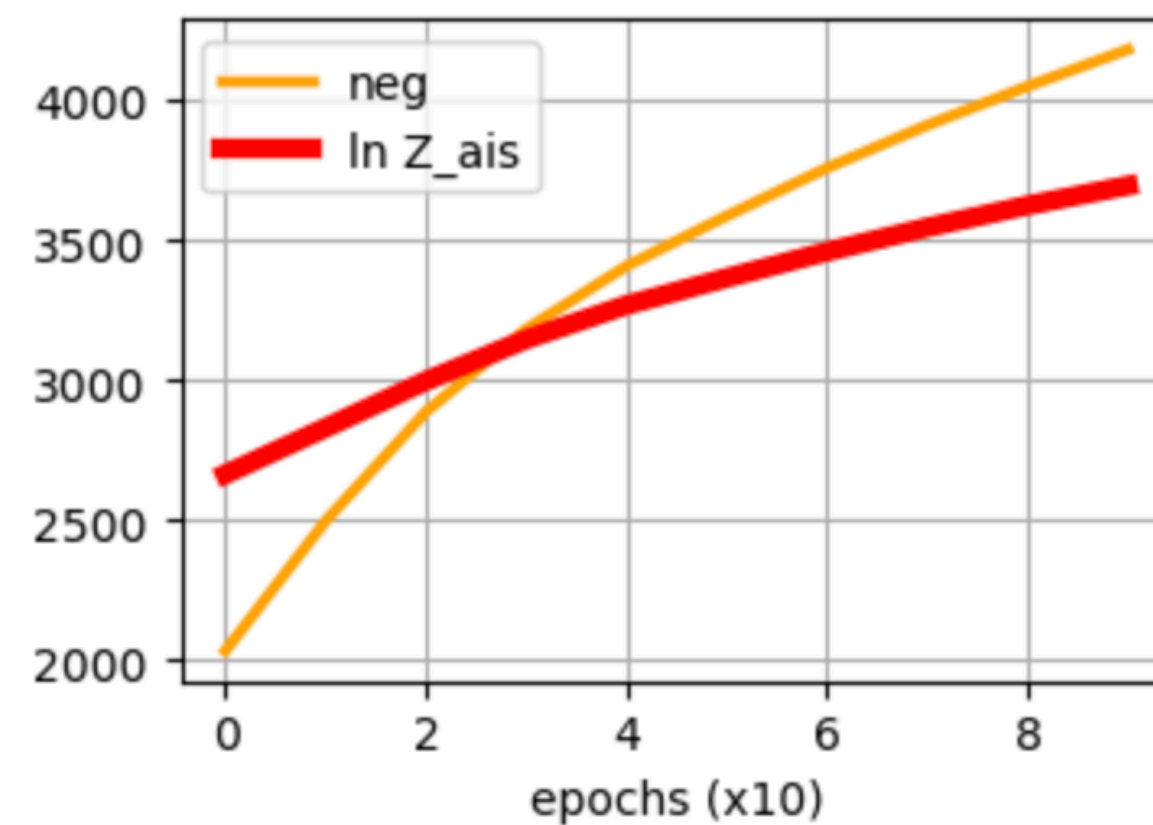
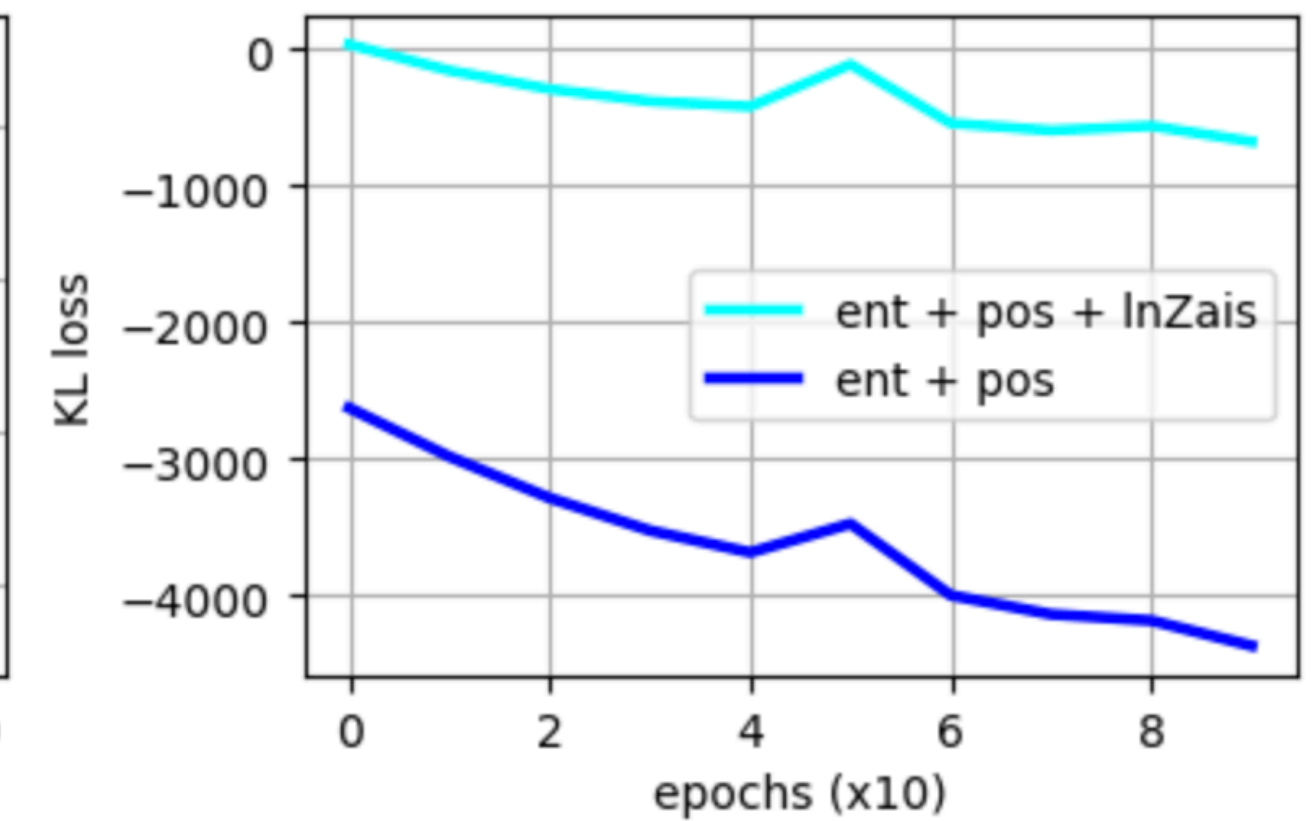
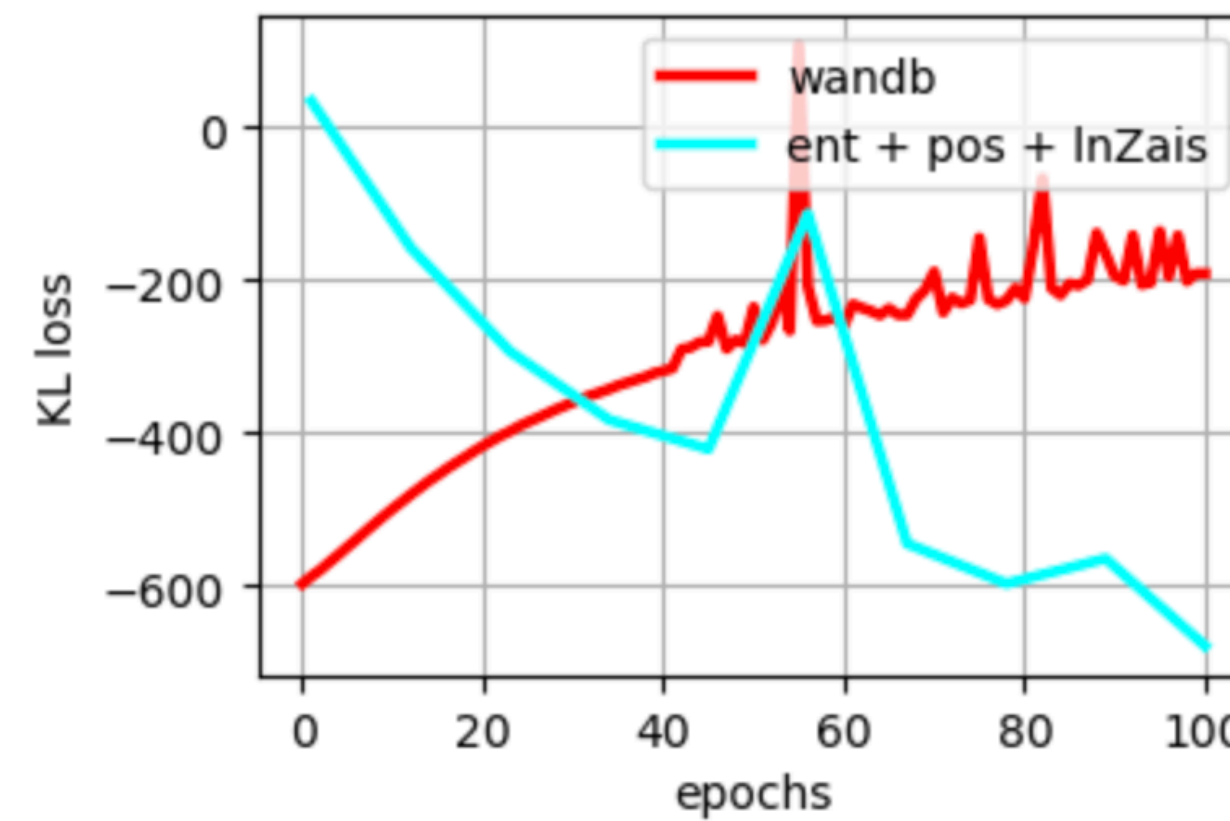
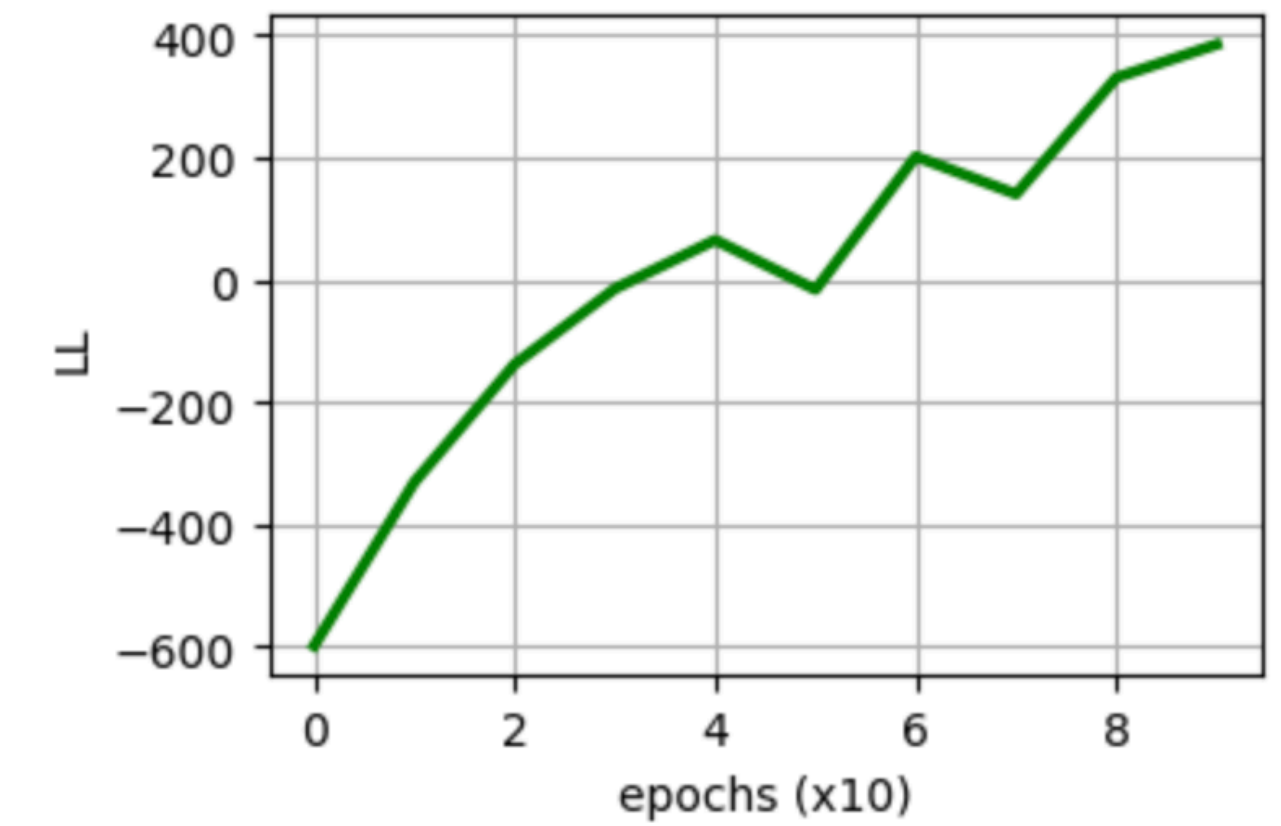
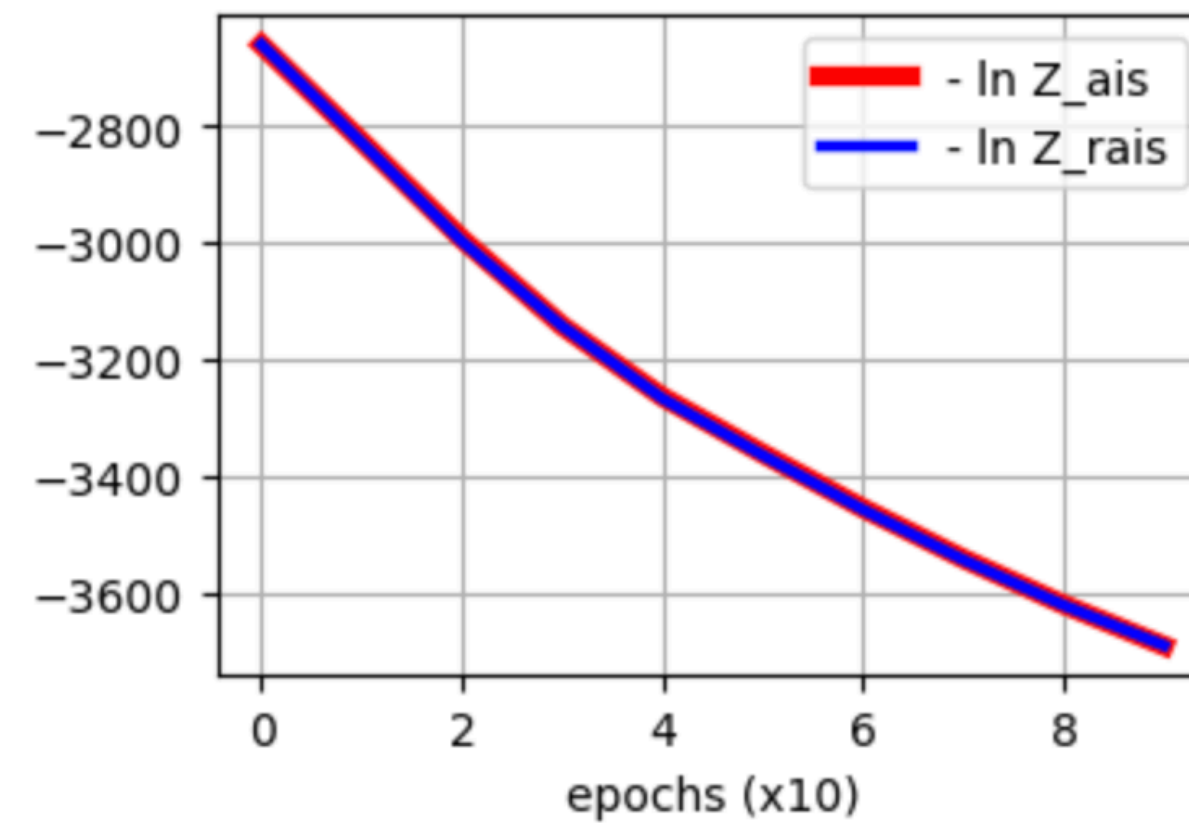
$\{z_i\}_{i=1}^N$: validation dataset

$$L: p(\{z_i\}) = \prod_{i=1}^N p(z_i) = \frac{1}{Z} \prod_{i=1}^N e^{-E(z_i)}$$

Z : partition function

$$LL = \langle \ln p(\{z_i\}) \rangle = \frac{1}{N} \left[-\sum_{i=1}^N E(z_i) - N \ln Z \right]$$

$$= -\langle E(z) \rangle_{\{z_i\}} - \ln Z$$



confused-
sponge-256

CNN+posEnc cond
VAE+scaled data

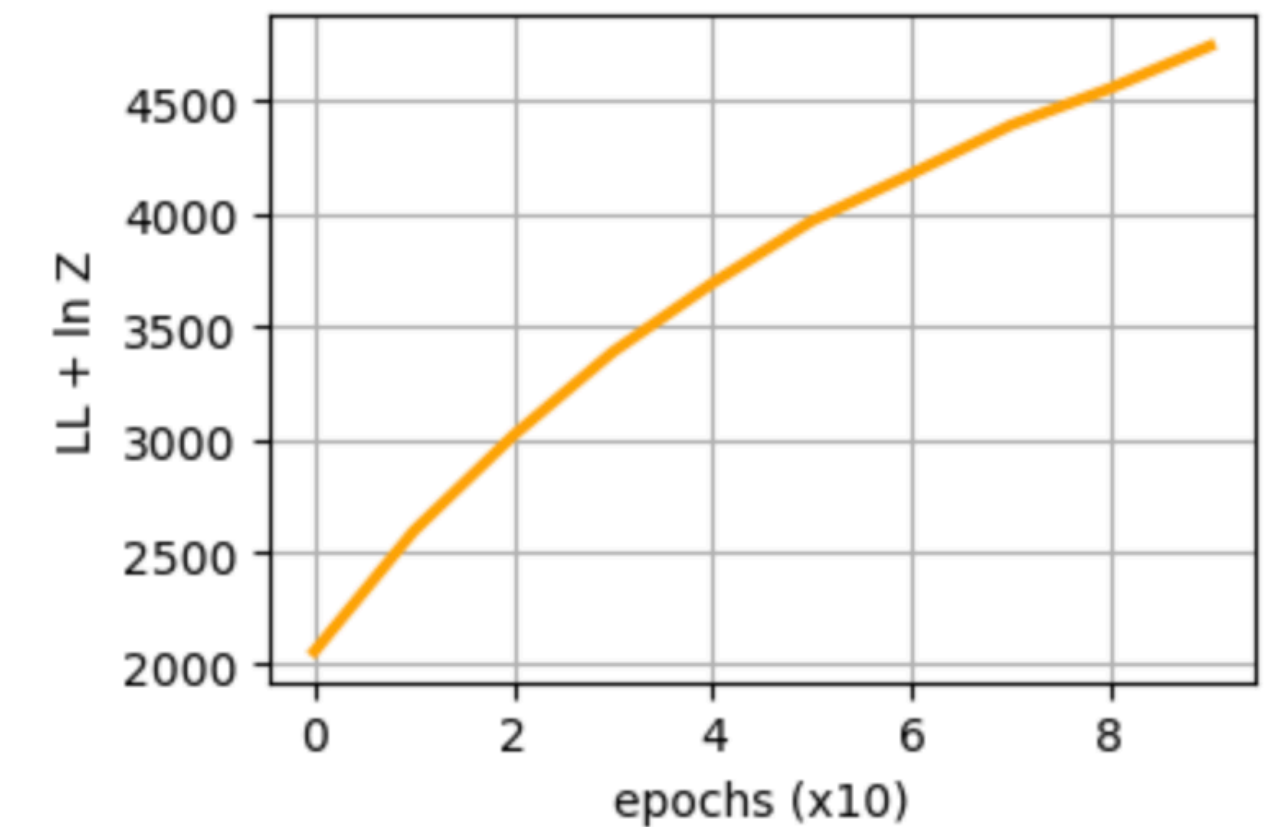
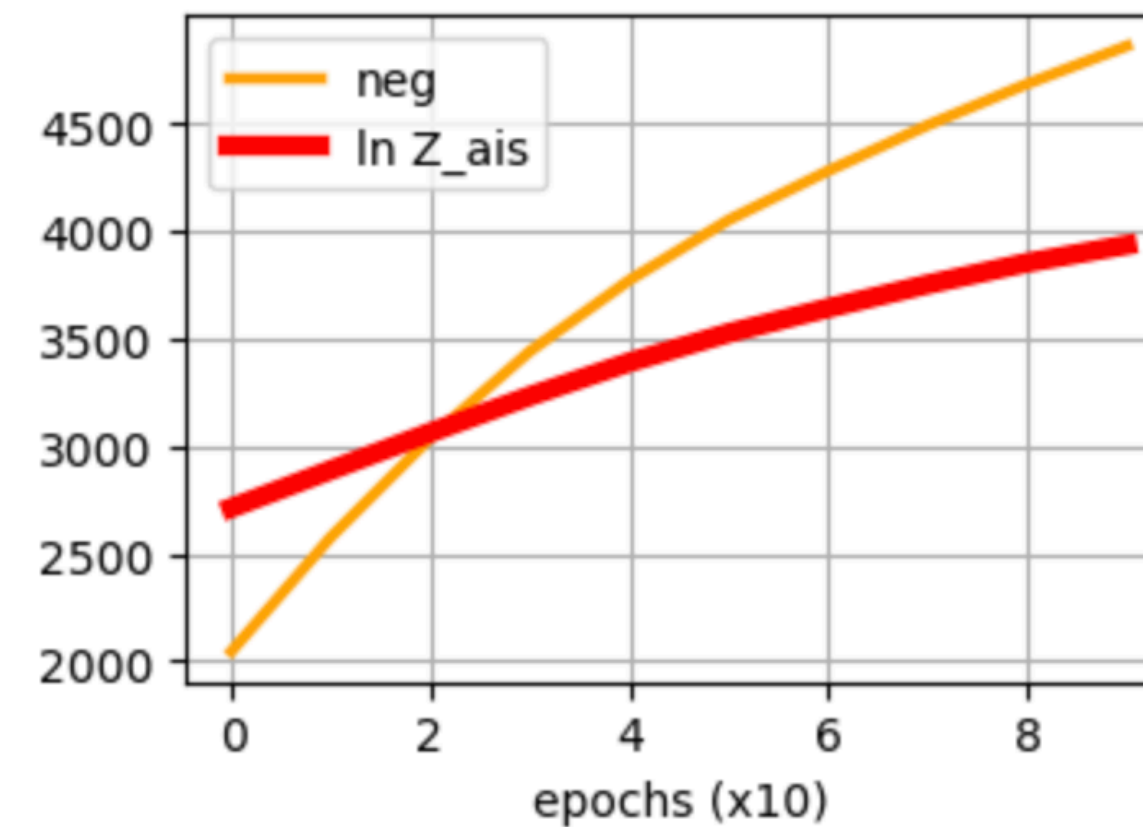
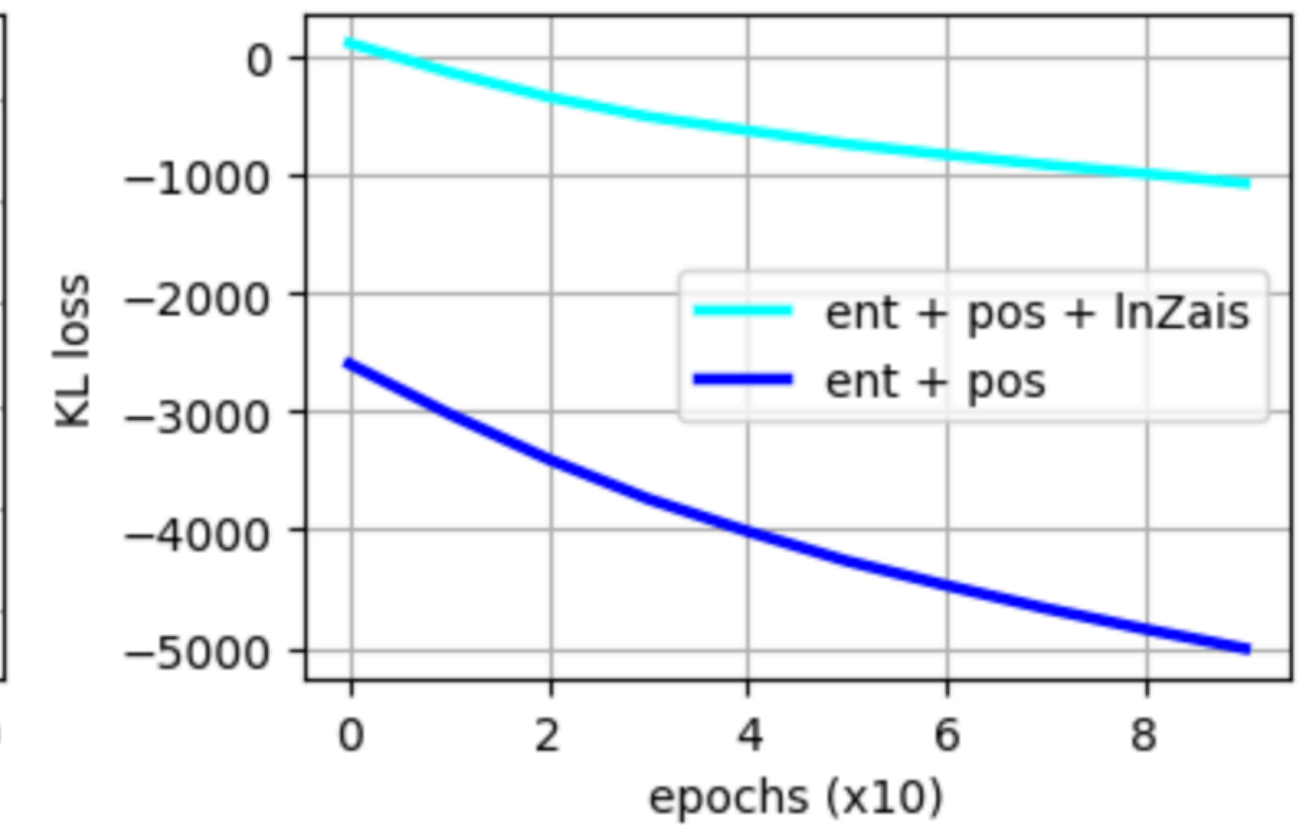
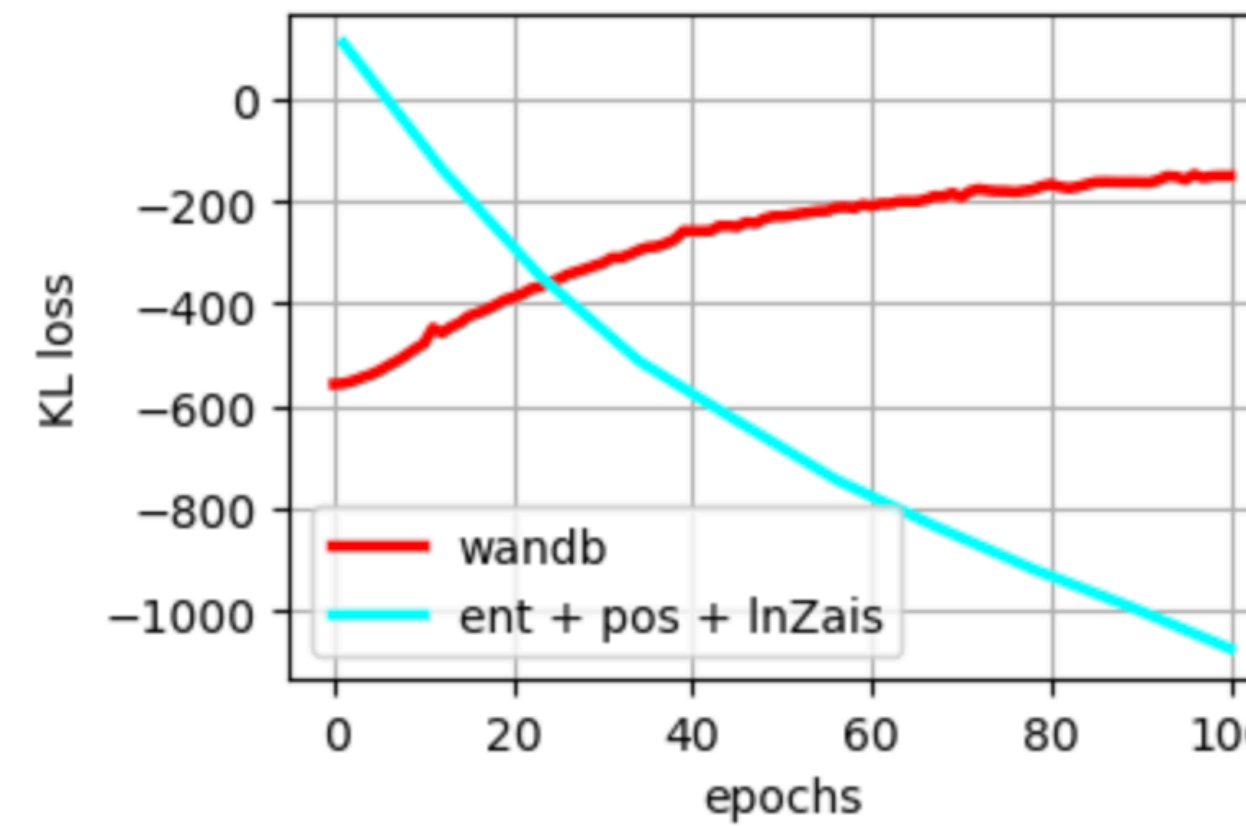
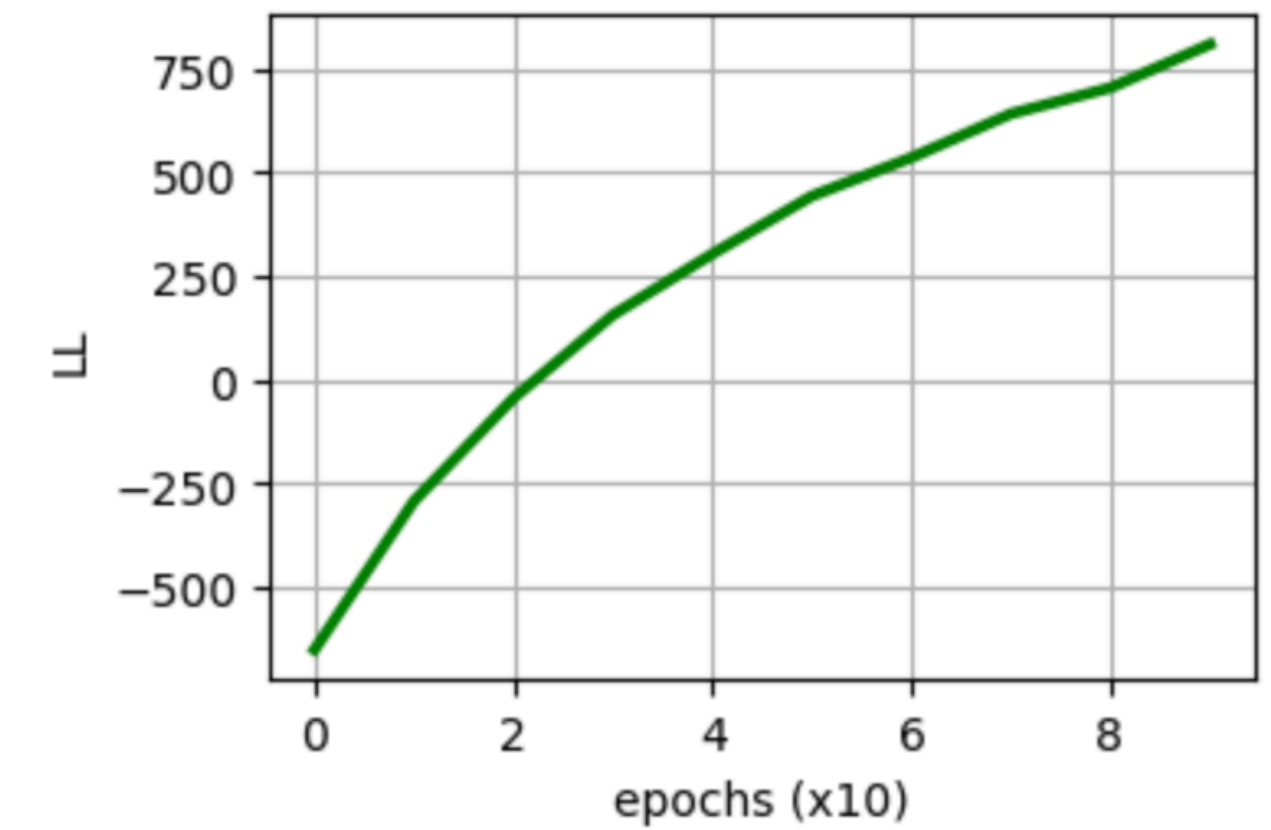
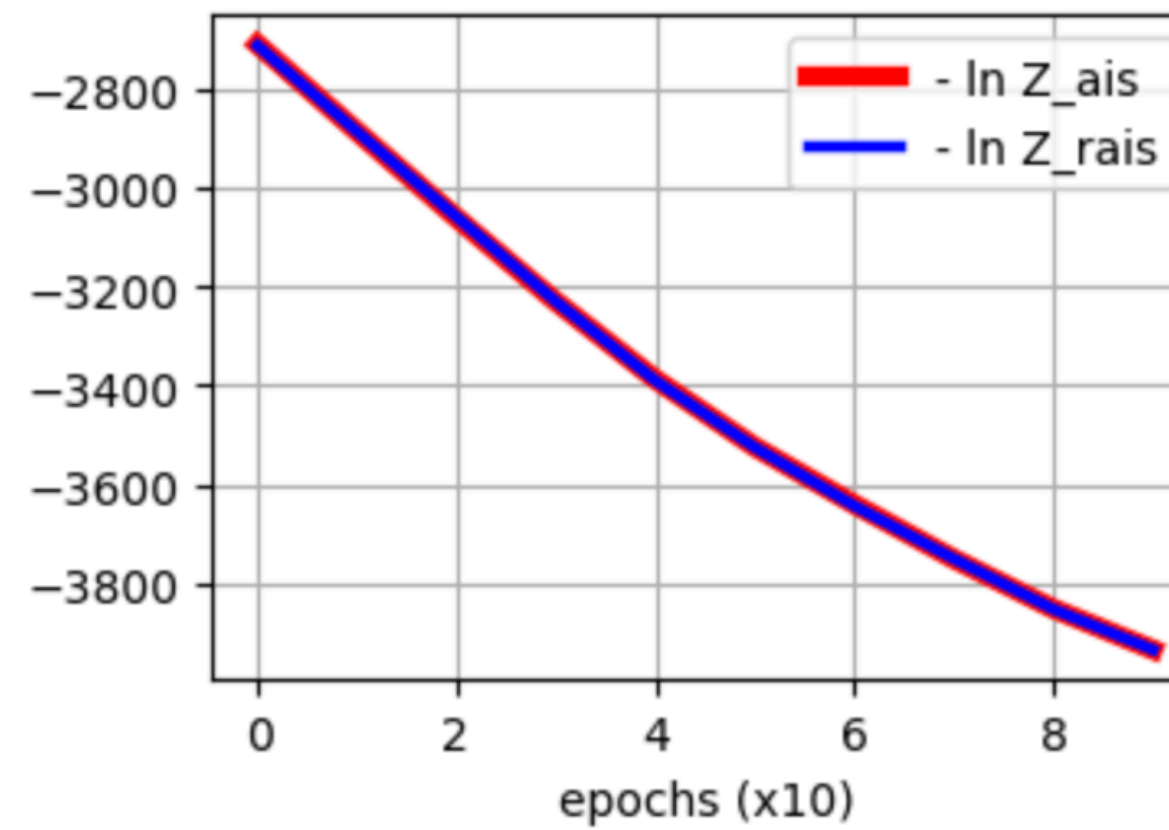
$\{z_i\}_{i=1}^N$: validation dataset

$$L: p(\{z_i\}) = \prod_{i=1}^N p(z_i) = \frac{1}{Z_1^N} \prod_{i=1}^N e^{-E(z_i)}$$

Z_1 : partition function

$$LL = \langle \ln p(\{z_i\}) \rangle = \frac{1}{N} \left[-\sum_{i=1}^N E(z_i) - N \ln Z_1 \right]$$

$$= -\langle E(z) \rangle_{\{z_i\}} - \ln Z_1$$



Things to do

- Make code lighter
- More work needed on the Positional Encoding
- I suggest increasing annealing rates.
- Save loss function data
- Save backup model after each epoch.
- What defines our best model during training?