

DAQ and electronics

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GRIDS 2026

Data AcQuisition

- Convert a physical signal into data that can be analysed
- This talk will try to illuminate this black box



DAQ now

- Almost universal approach
 - Convert physical phenomenon into **electrical signal**
 - Amplify/filter
 - Trigger
 - Simplify
 - Digitise
 - Write to disk
- The ordering can vary and some steps may be skipped

Before we dive in to the details

- Keep in mind that DAQ needs to be considered when you're designing your experiment
 - DAQ output must be sufficient for physics goals
 - Can be a large part of your budget!
- Your physics analysis and simulation also need to know about the DAQ
 - Deadtime? Pileup? Saturation? Efficiencies?
Resolution? Algorithmic decisions? Rounding?
- Even if it seems simple, there are probably subtleties...

Introduction

Signal manipulation

Triggering

Wiring and crates

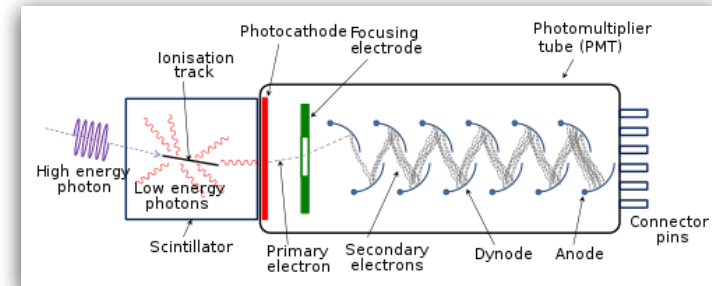
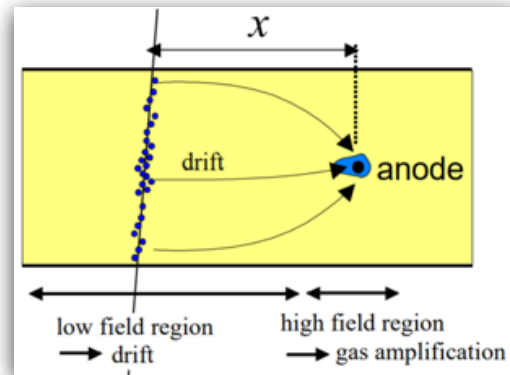
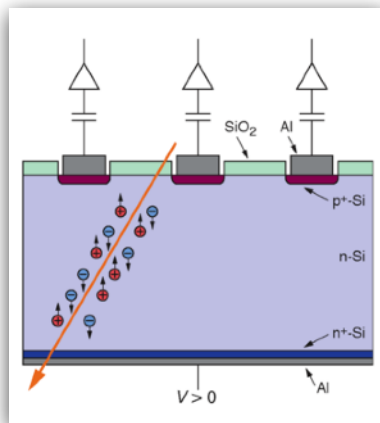
DAQ frameworks

Software and firmware

Example experiments

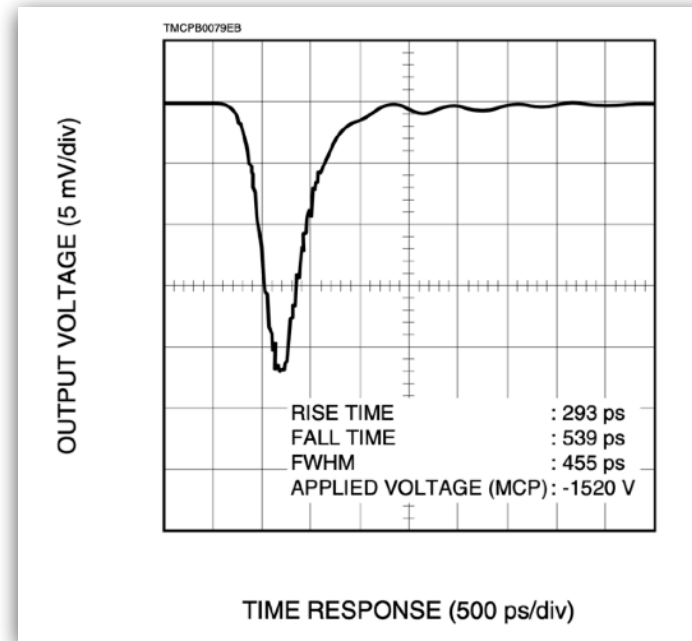
Electrical signals

- Electrical signals are well suited for transport, manipulation, digitisation
- Amplification within detector of 10^5 to 10^{10} typical
 - $Q_e = 1.6 \times 10^{-19} \text{ C}$; $100\text{mV} \times 10\text{ns} = 10^{-9} \text{ C}$
- See other lectures for how detectors convert physical phenomena to electrical signals



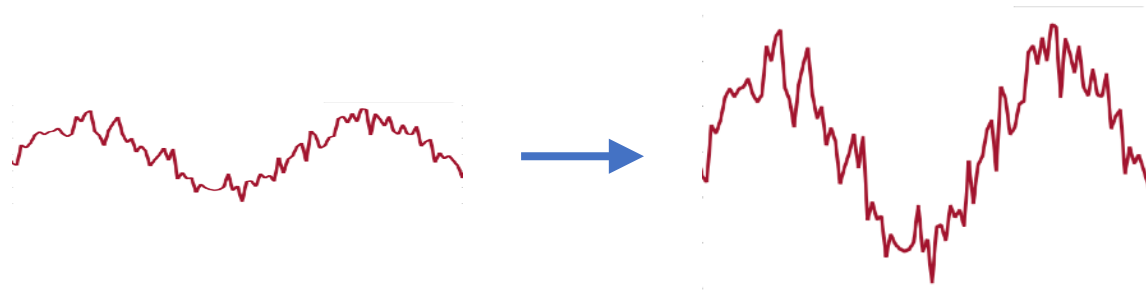
Typical detector signals

- Amplitude and time-scale vary based on device
- PMT and SiPM for a single photon $\sim 100\text{mV} \times 100\text{ns}$
- MCP for a single ion $\sim 10\text{mV} \times 1\text{ns}$



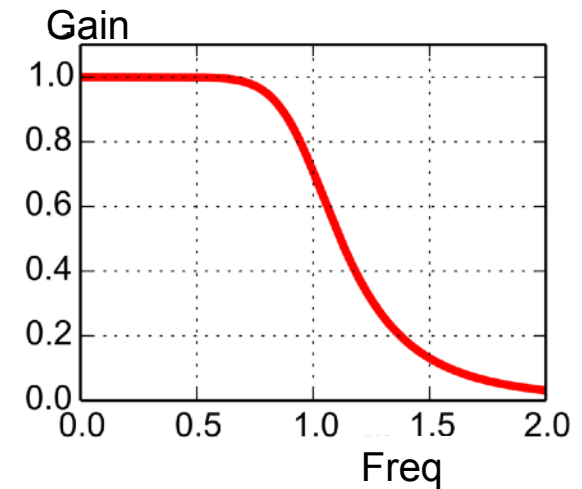
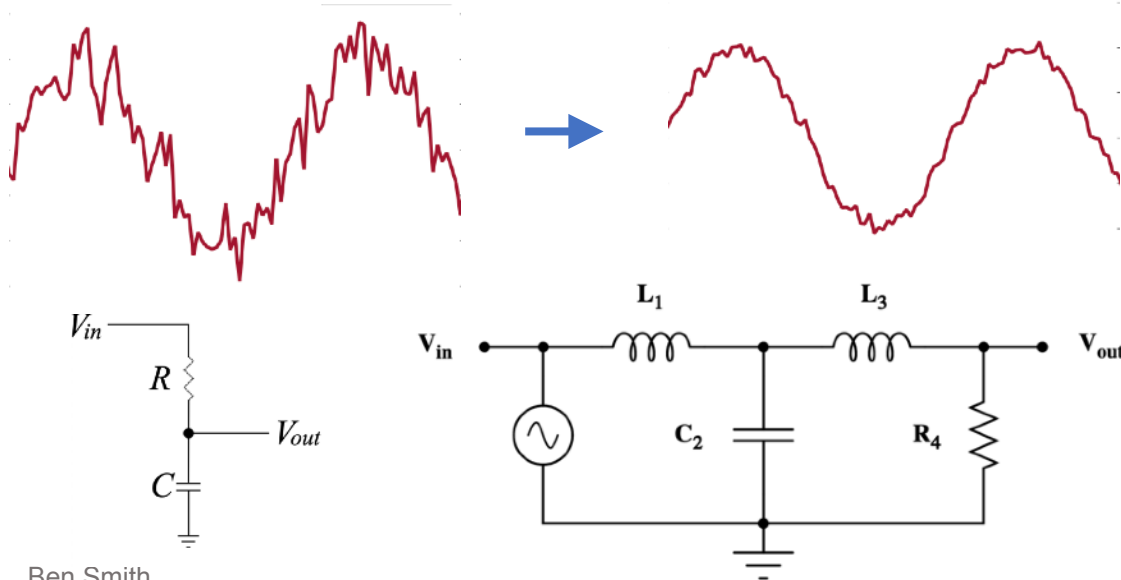
Amplification

- If signal is very small, may want to amplify it further
- Reduce impact of any noise introduced after amplification (e.g. while transmitting through cables)
- Better match subsequent electronics (e.g. digitiser has a +/- 2V range)



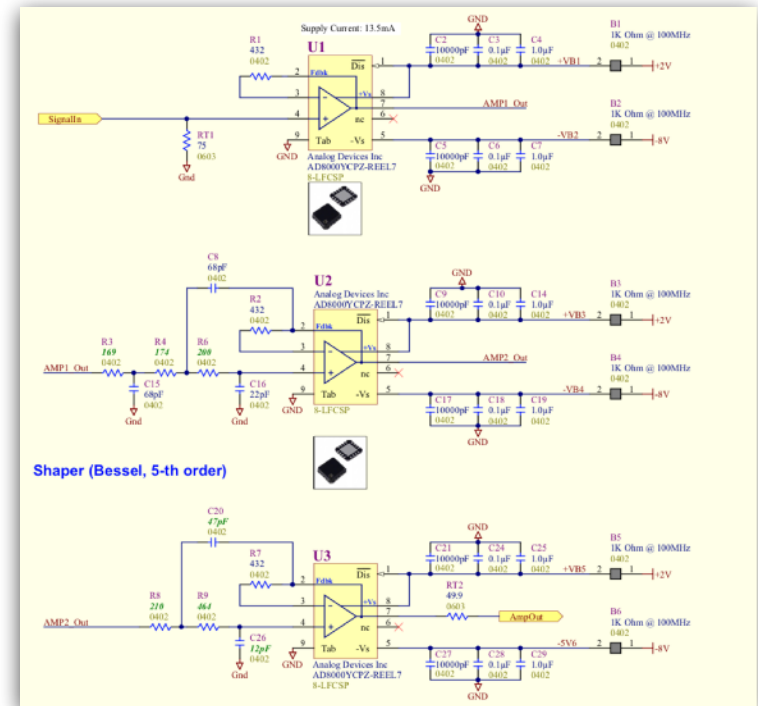
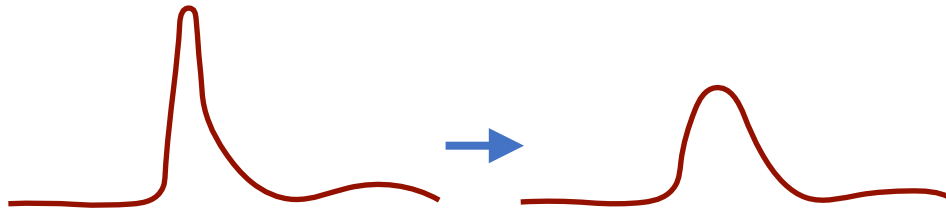
Filtering / noise reduction

- Can use a filter to reduce high-frequency noise without affecting low-frequency signal
- Can be as simple as resistor+capacitor, but "higher order" arrangements give better response



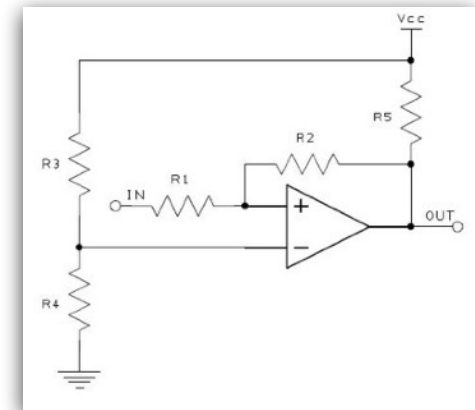
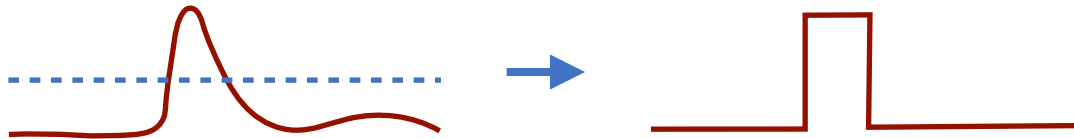
Shaping

- Can stretch a fast signal to take longer
- E.g. to better match time resolution of a digitiser
 - Very fast digitisers are very expensive!
- Amplifiers+capacitors+resistors



Threshold crossing - discriminators

- We've looked at analog electronics so far
- Discriminators convert an analog signal to a digital (0/1)
 - Easier to process and check for coincidences etc.
 - Good for detection and timing
- Simple discriminators implemented by comparing to a set voltage



Counting pulses - scalers/MCS

- Simplest thing you can do with digital signals - count!
- Visual / blind versions available
- Multi-channel scaler (MCS) has a terribly confusing name...
 - Should really be called a histogramming scaler
 - Counts pulses in each time bin (dwell time)



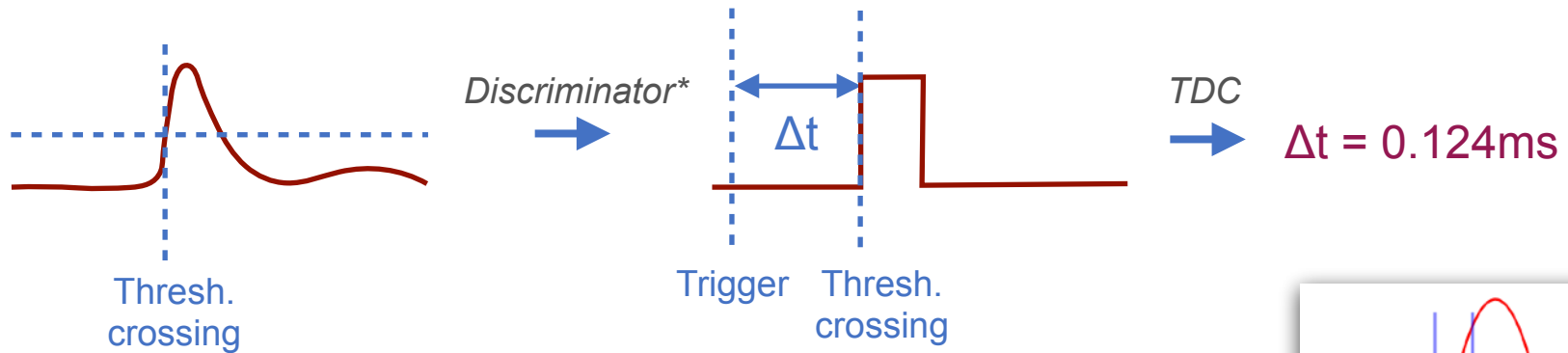
Visual scaler



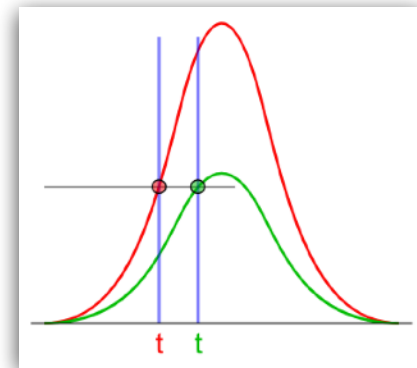
Blind MCS

Time of pulse - TDC

- Time to digital converter
- Tells you the time of a pulse relative to a trigger signal
- 3ps resolution now available commercially

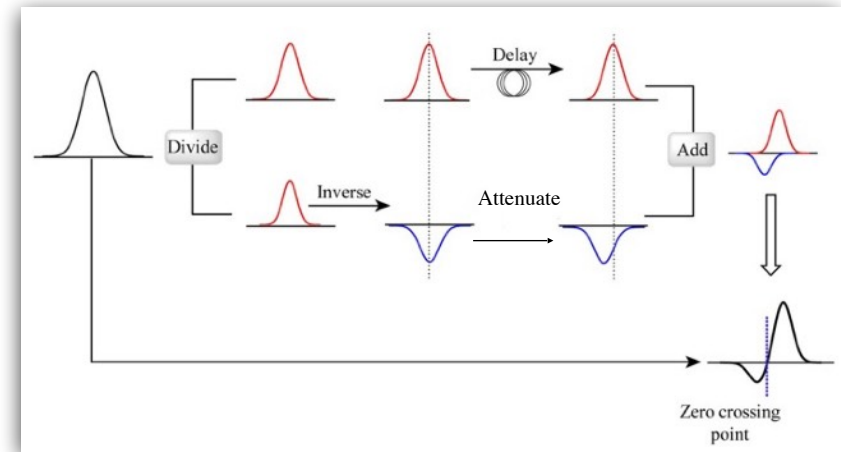
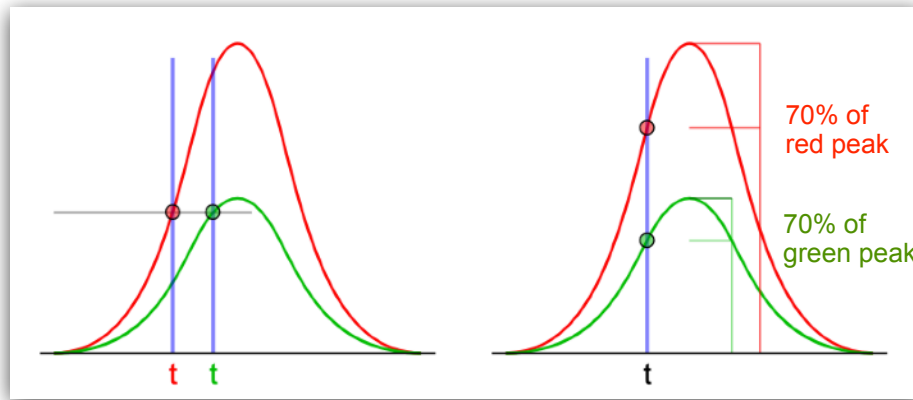


- Need to worry about time-walk effect if discriminator uses constant threshold voltage!



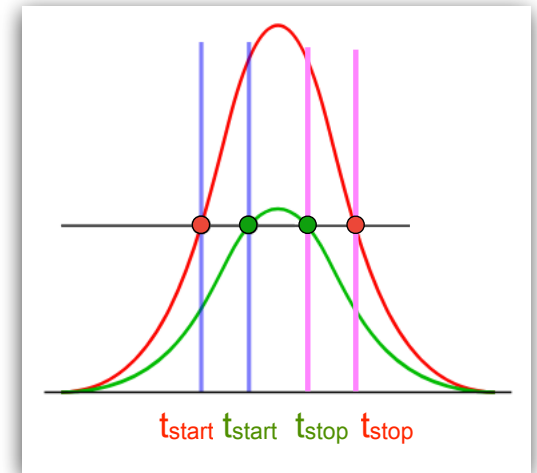
Constant fraction discriminator

- Classic approach to dealing with time-walk correction
- Trigger at X% of pulse height, rather than fixed voltage
- Only works if signal has same rise time regardless of amplitude - e.g. scintillators



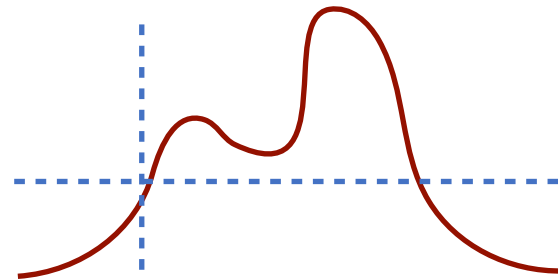
Alternative approach to time-walk

- Record start time and time-over-threshold for each pulse
 - Correlated with pulse charge / amplitude
- Do time-walk correction in software
- More flexible than CFD
 - Works even if pulse shape changes with amplitude
- You must have excellent knowledge of how your signal varies with amplitude!



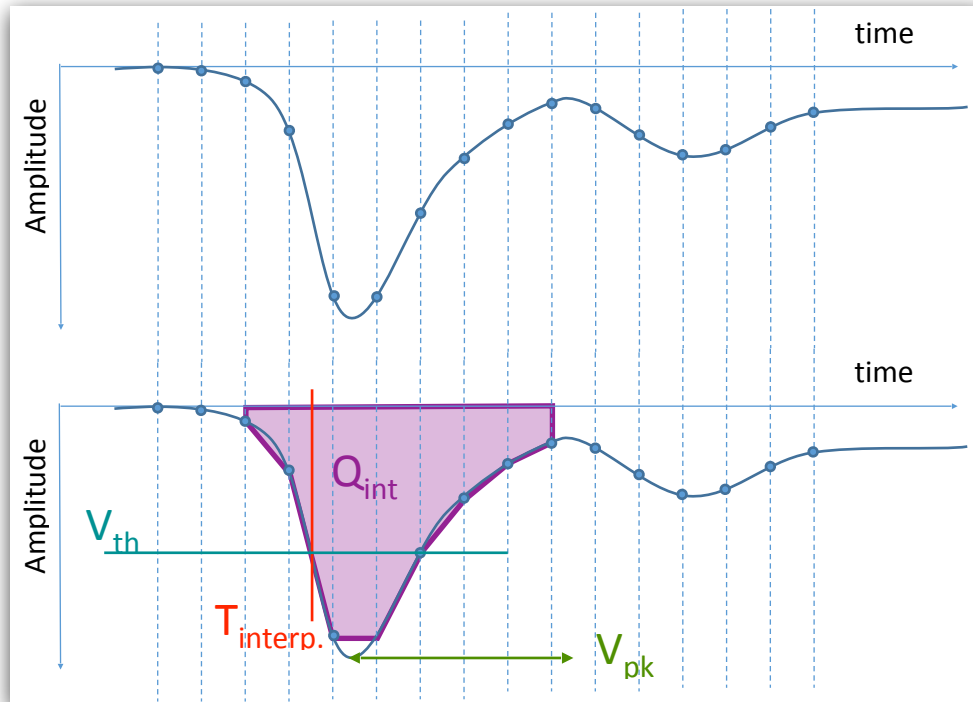
Pileup and complex waveforms

- Some experiments need to count every photon
 - E.g. dark matter experiments where signal is time distribution of ~ 100 photons
- Pileup of 2 photons is a problem for scaler/TDC - only get 1 count/timestamp!
- Need to either calculate the charge of the pulse (QT) or read out full waveform for offline analysis (digitiser)



ADCs / digitisers

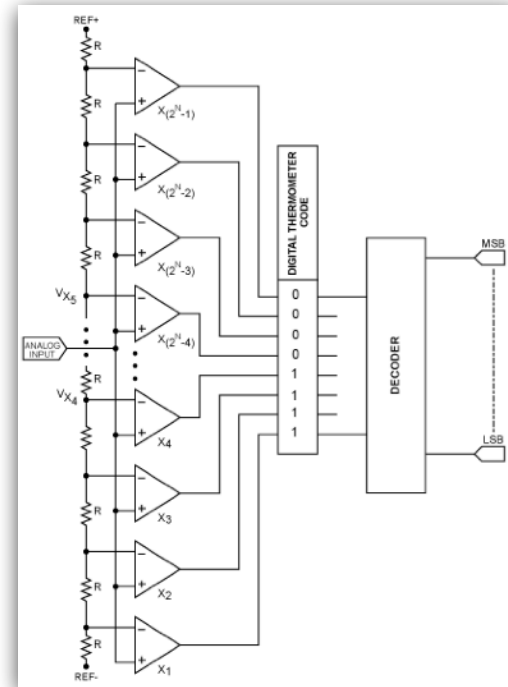
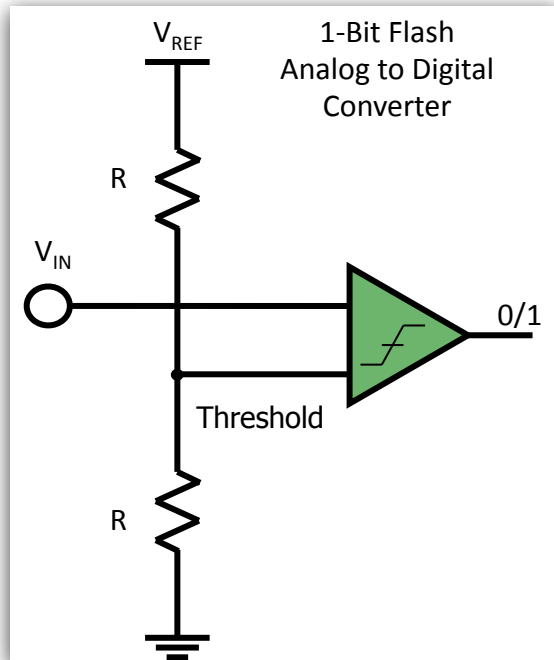
- Sample the waveform at specified sampling rate
- 10-bit resolution for 2V range: 2mV steps (4-bit: 125mV)



ADC Type	Resolution (bits)	Sampling rate
Dual Slope	12-20	100 sample/s
Successive approximation	8-18	10 Msample/s
Flash	4-12	10 Gsample/s
Pipeline	8-16	1 Gsample/s
Delta-sigma	8-32	1 Msample/s

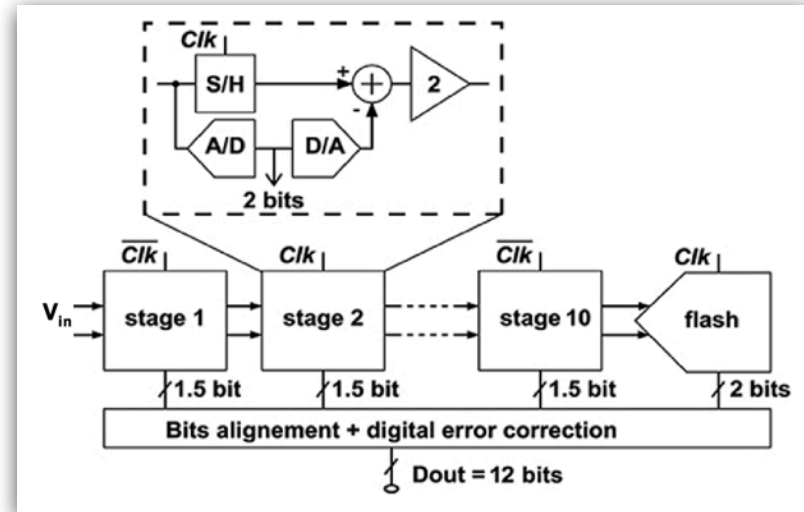
Flash ADC implementation

- Conceptually simple, but cost grows exponentially with resolution
- Need 2^{10} threshold comparators for 10-bit ADC!



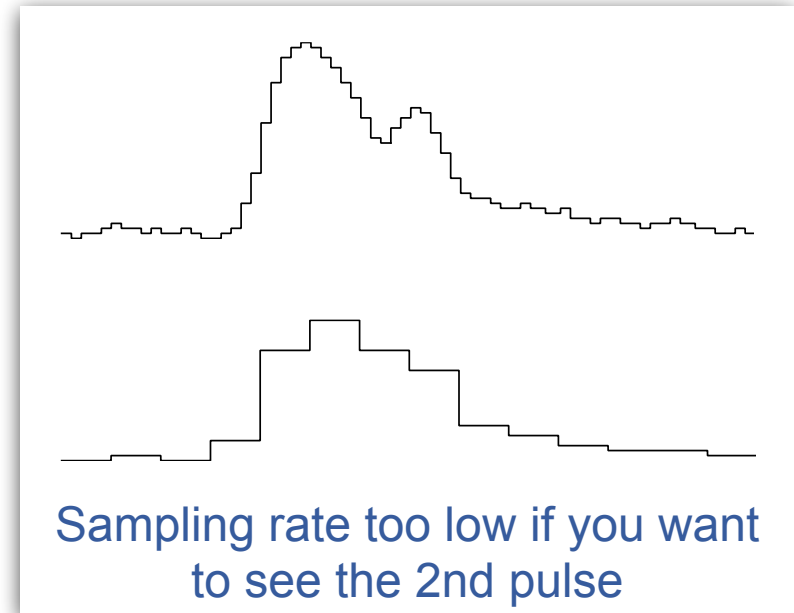
Pipeline ADC

- Use multiple few-bit flash ADCs in sequence
- Uses successive approximation. E.g.
 - Stage 1 is 1V resolution (say 2-3V)
 - Subtract 2V from signal
 - Stage 2 is 0.1V resolution (say 0.3-0.4V)
 - Final result is sum of all stages (say 2.3V)
- Much cheaper (cost grows linearly with resolution)
- But, there's a delay as voltage passes through stages
 - Might impact your trigger?



ADC considerations

- Sampling frequency
 - Need $f_{\text{sampling}} > 2 \times f_{\text{signal}}$ (Nyquist-Shannon theorem)
- Sampling delay
 - Impacts trigger logic?
- Dynamic range
 - Need to amplify signal?
- Dead time during readout
 - Only for some ADC types



Recap of possible outputs

- Discriminator + scaler
 - Number of pulses
- Discriminator + multi-channel scaler
 - Number of pulses in each time bin
- Discriminator + TDC
 - Time of each pulse (as a list)
- ADC/digitizer
 - Waveform of each pulse (at some time base and voltage resolution)



```
0x1000, 0x1001, 0x1004, 0x100a, 0x1014, 0x1010, 0x1007,
0x1002, 0x1000, 0x1002, 0x1003, 0x100b, 0x1015, 0x1011,
0x1008, 0x1003, 0x1001, 0x1000, 0x1001, 0x1000, 0x1001,
0x1000, 0x1001, 0x1004, 0x100a, 0x1014, 0x1010, 0x1007,
0x1002, 0x1000, 0x1002, 0x1003, 0x100b, 0x1015, 0x1011,
0x1008, 0x1003, 0x1001, 0x1000, 0x1001, 0x1000, 0x1001,
0x1000, 0x1001, 0x1004, 0x100a, 0x1014, 0x1010, 0x1007,
0x1002, 0x1000, 0x1002, 0x1003, 0x100b, 0x1015, 0x1011,
0x1008, 0x1003, 0x1001, 0x1000, 0x1001, 0x1000, 0x1001,
```

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Wiring and crates

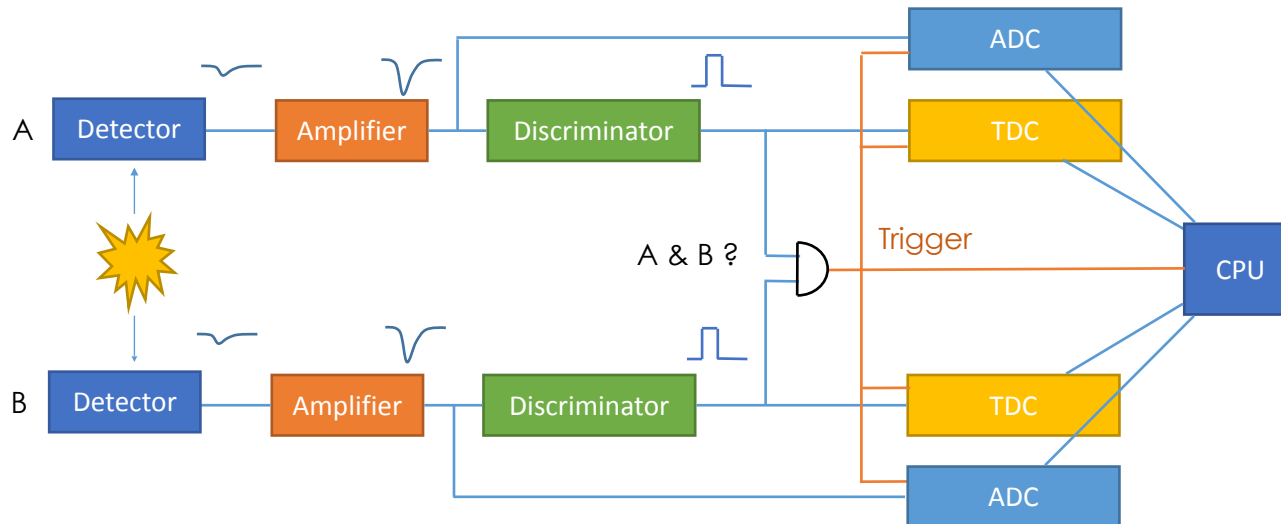
DAQ frameworks

Software and firmware

Example experiments

Event-based (internal) triggering

- Detectors produce continuous electrical signals
- Reduce data rate enormously if you only trigger data readout when something "interesting" happens
- Event-based triggering uses detector signals themselves to decide when to trigger (e.g. a coincidence between channels)



External trigger

- Trigger may be even easier if your experiment uses laser pulses / particle beam pulses
- Can work in both directions
 - DAQ tells laser/beam to pulse
 - Laser/beam tells DAQ that it has pulsed
- Either way, you can trigger your electronics using that same signal

Trigger-less DAQ

- Used in some large-scale experiments (that don't have the same resources as LHC experiments)
 - Thousands/millions of detector channels
 - Too much activity to make a coincidence trigger
- Don't use a global trigger at all
- Each channel triggers independently
 - Read out every single hit (stream is many GB/s)
 - Reconstruct events in server farm
 - Decide what data to save (few MB/s)

Why does data reduction matter?

- Data builds up quickly for experiments that run 24/7
 - 60MB/s is 2PB/yr
- Costs \$\$\$ to store data
- Simpler data is easier and faster to process/analyse
- BUT, you have to understand your detector
 - Experiments often start off recording lots of data, then implement more aggressive reduction once they've proved that the "lost" information doesn't affect the science analysis

How much can you simplify?

- BetaNMR use multi-channel scalers, sum up the histograms in software, and only save those summed histograms
 - Written 1.5GB total since 2000
- Darkside-20k have thousands of channels and record the time/charge of each pulse
 - Write the same amount of data per second as BetaNMR write per year!

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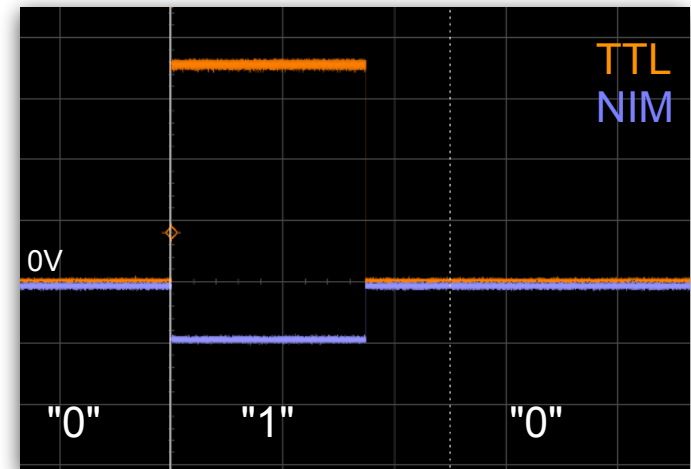
Software and firmware

Example experiments

Digital levels

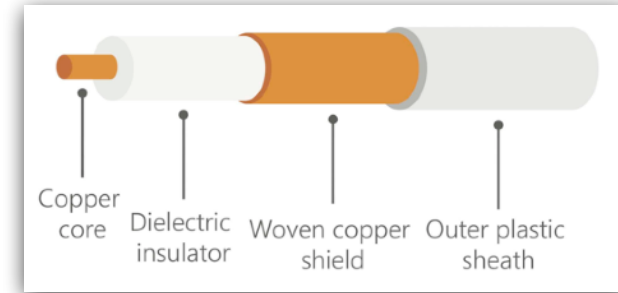
- Different standards evolved over time
 - Available technology, speed, power consumption...
 - NIM/TTL are the most common in physics
- Level translators available if you need to mix

Standard	Digital 0	Digital 1
NIM	0 V	-0.8 to -1 V
TTL	0 to +0.7 V	+1.5 to +5 V
ECL	-1.75 V	-0.9 V



Cables and connectors

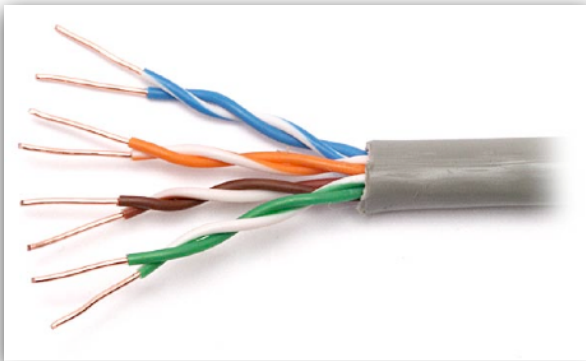
- Most signals transmitted using coaxial cables
- Different connector options
 - SHV is for safe high voltage connections
 - LEMO 00 is very often used in physics
 - Latches into the receiver
 - Pull the outer housing, not the cable!
 - BNC also common
 - Larger but cheaper



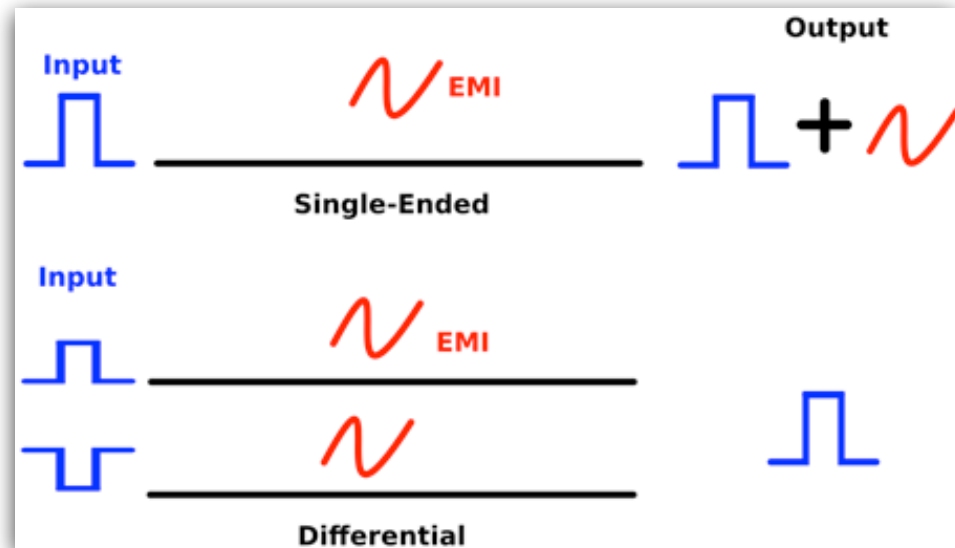
Description	Price
LEMO 00 - LEMO 00 Single Probe Transducer Cable, 4 foot length	\$85.00

LVDS

- Low voltage *differential* signalling
- Instead of sending +2V, send (A) +1V and (B) -1V
 - Receiver does (A-B) to get +2V
 - But any "pickup noise" is cancelled out!
- Usually implemented in a "twisted pair" cable



Ben Smith

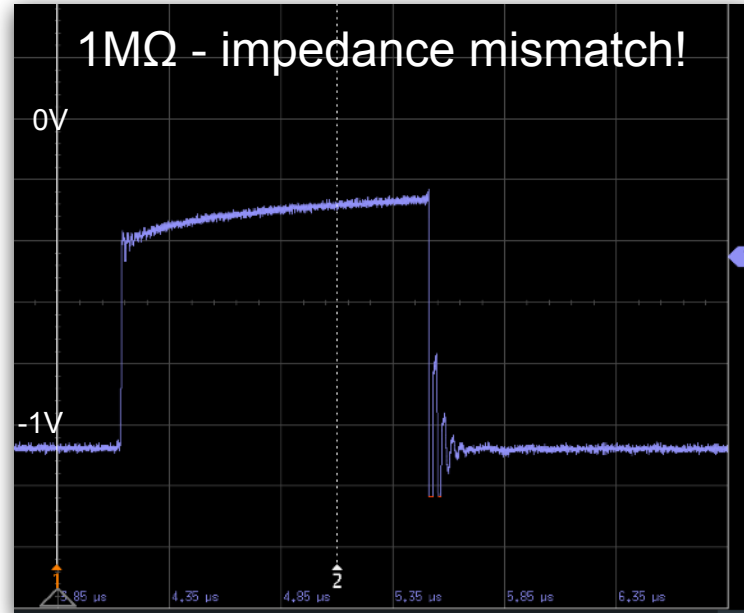
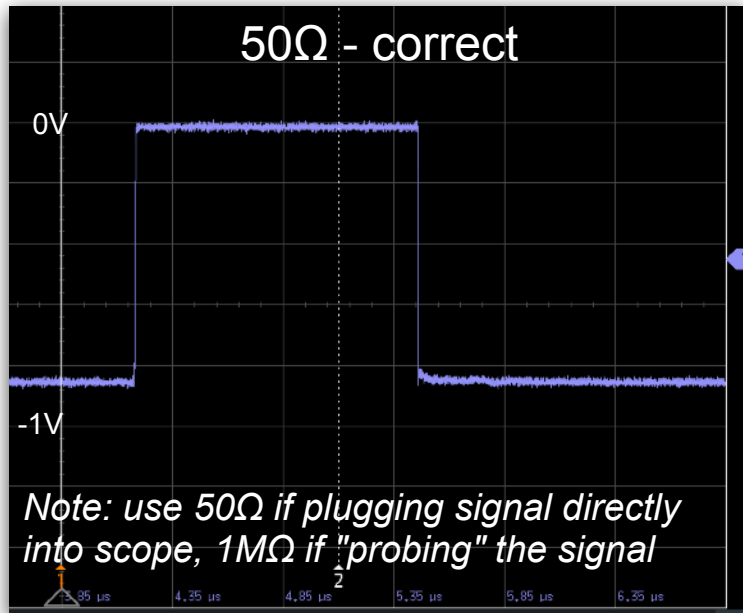


Impedance matching and reflections

- Impedance (Z) is the complex version of resistance
 - $Z = R + jX$; R is resistance (DC); X is reactance (AC)
 - Ideally resistors are pure- R , capacitors are pure- X
 - Reactance varies with frequency of signal
- If there's a mismatch between source/cable/receiver, can get reflections in the signal
- Almost all devices/connectors you'll use are 50Ω
 - Beware - RF systems often use 75Ω

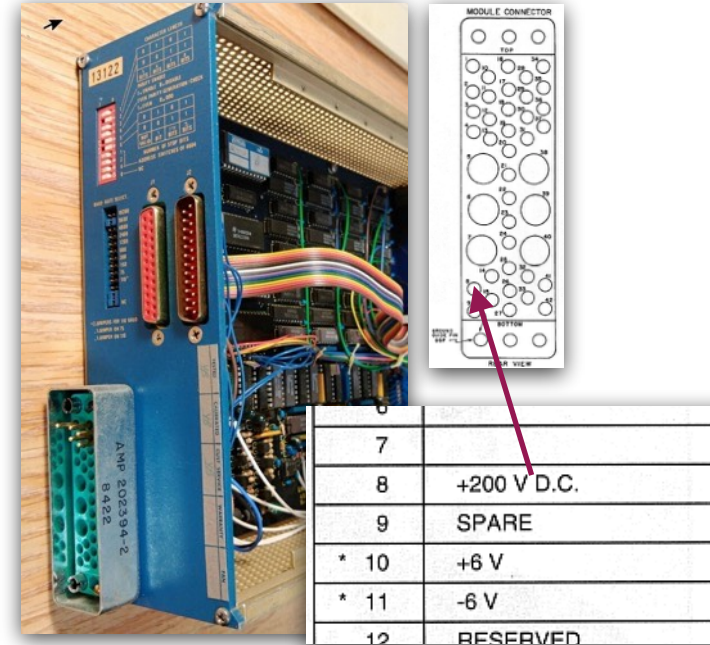
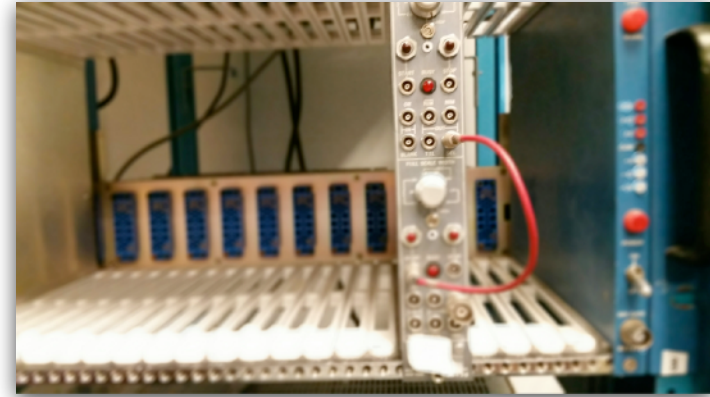
But I don't design electronics or deal with RF...

- The impedance mismatches you're likely to see are:
 - Oscilloscope being in 1M Ω termination instead of 50 Ω
 - Forgetting to terminate daisy-chains



NIM crates

- Very simple (and old) standard
- Provides power to NIM modules through a standardised connector
 - One of the power pins is 200V!!
- Many modules available
 - Amplifier, discriminator, fan-out, coincidence, scaler, ...
- Not used much outside physics



"NIM" has two meanings - crate and voltage levels!

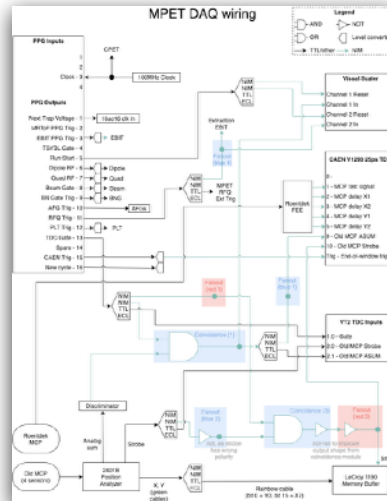
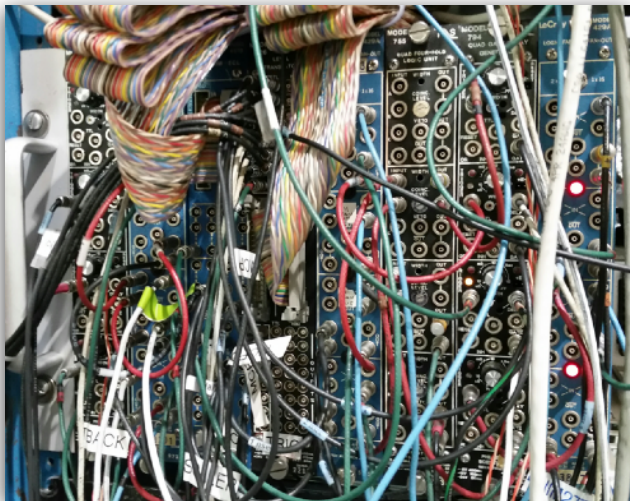
Backplane-based crates

- Backplane allows boards to talk to each other
 - Often put a single-board computer in the crate to read out data from all boards
- VME (1981)
 - Still used in physics, military, railroads...
 - Max ~ 1Gb/s through backplane (generally less)
 - Some boards now only use backplane for power - read data out via ethernet
- uTCA (2003)
 - Developed by telecommunications industry
 - Higher data rate through backplane (100Gb/s)



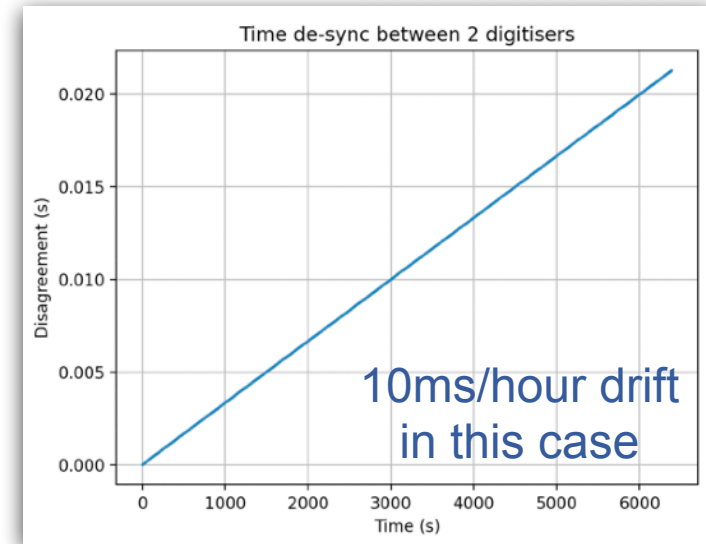
Wiring top tips

- Can be time-consuming to trace the logic
 - Make a diagram and label your cables
 - drawio.com is a great tool
- Labs have lots of modules lying around that are OLD!
 - Assume every connection is bad until checked...



A quick word about clocks

- Many devices have on-board clocks
- These are generally quite inaccurate and *will* drift
 - Bad if you need to correlate data from multiple boards
- If you have multiple devices, use one as the master and distribute that clock signal to others
- If you need true and stable, use a Rb clock or similar
- If you need the true "real world" time (e.g. for supernova search) use GPS



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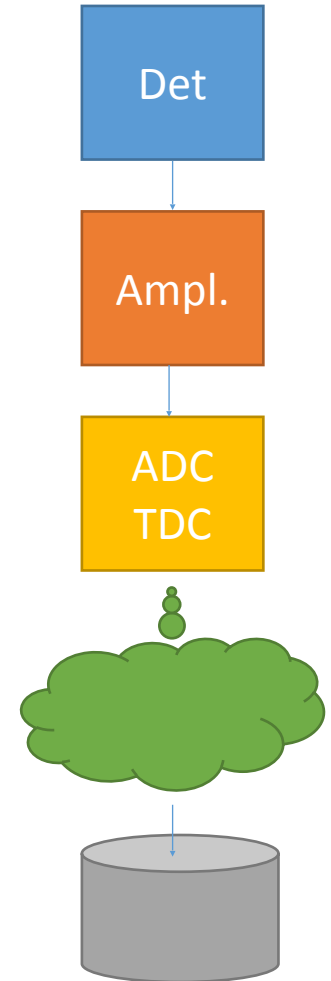
DAQ frameworks

Software and firmware

Example experiments

Final piece of the puzzle

- Need to read data from digitisers, TDCs etc and store on disk for final physics analysis
- Often want to combine data from multiple detectors into a single "event"
- Generally acquire data in "runs" with specific experimental conditions
 - E.g. PMT voltages, calibration source location, beam energy, ...
- Several frameworks available to help

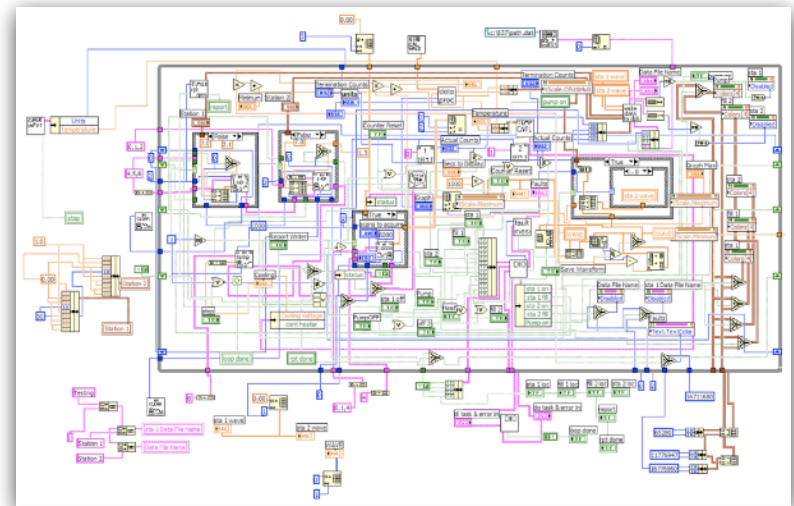
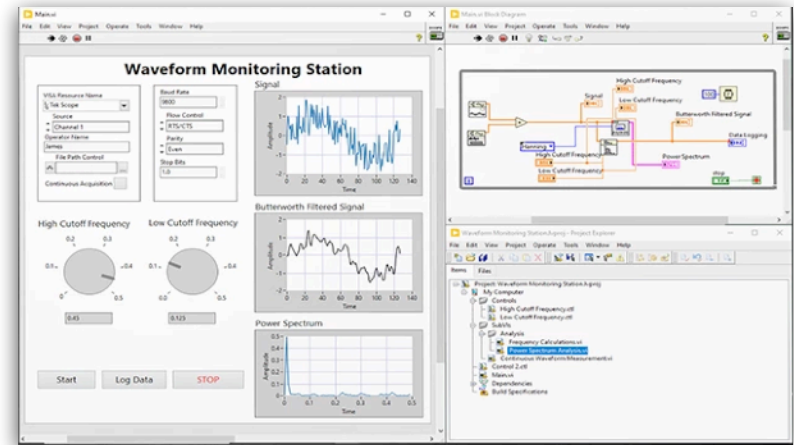


What we want from a DAQ framework

- Read data from many types of hardware
- Configure devices and store the configuration
 - Including "slow control" of voltages,
- Collect data from many devices into a single "event"
 - Multiple programs, possibly on multiple computers
- Stable - will it still work in 10 years?
- Efficient and performant - GB/s input?
- Nice to have - alarms, event displays, web interface, ...

LabView

- "Low code" proprietary system by National Instruments
- All NI devices will come with a LabView driver
- Simple to setup tabletop experiments
- Does not scale well for experiments that need high speed, complex logic, many devices, or use Linux



Other DAQ frameworks

- Many labs have developed their own systems

Framework	Developed by	Written in	Used by
ORCA	North Carolina	Objective-C (MacOS only)	Katrin, Majorana, SNO+, ...
artdaq	Fermilab	C++	Lariat, mu2e, SBND, ...
CODA	Jefferson	Java (plus need special VME hardware)	JLab
MIDAS NewGen	Rutherford	Tcl	Rutherford
MIDAS	PSI/TRIUMF	C++ and python	mu3e, T2K, Alpha-G, MEG, Darkside, ...

MIDAS

- Maximum Integrated Data Acquisition System
- Very customisable
 - Can implement data readout in C++ or python
 - Webpages in javascript
- Free (GPL)
- Good for 1-50 computers and ~ 1GB/s data rate

The screenshot displays the MIDAS web interface for a system named 'ds'. The top right corner shows 'Alarms: None' and the date '13 Jun 2022, 22:19:57 UTC+2'. The left sidebar contains navigation options: Status, Transition, ODB, Messages, Chat, Alarms, Programs, Buffers, History, Sequencer, Config, Event Dump, Save and load, CAEN SY1527, CAEN VX2740, PDU Plus, PDU Slim, ELOG, dsanana, Runviewer, and b01 firmware.

Run Status

Run 1327	Start: Mon Jun 13 21:39:47 2022	Stop: Mon Jun 13 21:41:02 2022
Stopped	Alarms: On	Restart: Off
Start	Data dir: /storage/dsdata/setup-2/sandbox	

Experiment Name: **DarkSide Setup-2 (ds)**

Run type: self-trigger
 Shifter: ZB AC ES
 Light level: Off
 Comment: fully populated pdu,138.5 V, all tiles on for all quadrants, 5.6us window, DARKSIDE FIRMWARE, 48-sample moving average
 Write Data: false

1655149264 21:41:04.045 2022/06/13 [rvprovider,LOG] Program rvprovider on host darkside-daq stopped

Equipment

Equipment +	Status	Events	Events[/s]	Data[MB/s]
VX2740_Config_Group_000	VX2740_Group_00@darkside-daq.na.infn.it	13	0.0	0.000
VX2740_Data_Group_000	VX2740_Group_00@darkside-daq.na.infn.it	158933	0.0	0.000
EpicsFrontend	EpicsFrontend@darkside-daq.na.infn.it	0	0.0	0.000
SteeringModulePDUslim	Frontend stopped	0	0.0	0.000
SteeringModule	Frontend stopped	0	0.0	0.000
CAEN_HV	Frontend stopped	0	0.0	0.000
SteeringModulePDUPlus	SteeringModulePDUPlus@darkside-daq.na.infn.it	0	0.0	0.000

Logging Channels

Channel	Events	MB written	Compr.	Disk Level
#0: run01326sub0000.mid	0	0.000	0.0%	27.6%
Lazy Label	Progress	File Name	# Files	Total
runcopy	0.0%	run01326sub0000.mid	4155	0.0%

Clients

saveload [darkside-daq.na.infn.it]	Sequencer [darkside-daq.na.infn.it]	EpicsFrontend [darkside-daq.na.infn.it]
SteeringModulePDUPlus [darkside-daq.na.infn.it]	Logger [darkside-daq.na.infn.it]	VX2740_Group_00 [darkside-daq.na.infn.it]
mhttpd [darkside-daq.na.infn.it]	Lazy_runcopy [darkside-daq.na.infn.it]	mserver [darkside-daq.na.infn.it]

MIDAS webpages

Status Page

Program Sample Frontend on host localhost started

Alarms: OFF

Run Status: Run #2 Running, Start: Fri Jan 5 16:53:56 2018, Running time: 71h26m16s

Equipment	Status	Events	Events/s	Data(MB/s)
Scaler	Running	1413	89.5	0.005
Sample Frontend@localhost	Running	2	0.0	0.000

Logging Channels: Channel: run0002.msd, Events: 99.7%, Compr.: 91.2%, Disk Level: Total

Alarm Page

Reset all alarms | Disable the alarm system | Play sound

Alarm	State	First triggered	Class	Condition	Current value
HV	Triggered	Mon Jan 8 16:27:33 2018	Alarm	/Equipment/Scaler/Variables/SCLR[0] > 100	586152121

Program alarms:

Alarm	State	First triggered	Class	Condition
Sample Frontend	Triggered	Fri Jan 5 17:22:10 2018	Alarm	Program not running

Internal alarms:

Alarm	State	First triggered	Class	Condition/Message
Shift check	Triggered	Mon Jan 8 16:27:33 2018	Warning	Please do your shift checks

History Display

Group: Xenon | Panel: Xe pressures | Keep horizontal axis when switching panels

Xenon - Xe pressures

Det Press 0: 0.125909
Det Press 1: 0.126068
GM Press: 0.127191

Xenon.GM Press: 0.127191

30 May 22 | 31 May 22 | 31 May 22, 15:26:11 | 02 Jun 22

Configuration Editor

Run #2 stopped

Alarms: OFF

Online Database Browser

Find | Create | Delete | Create Elog from this page

Runinfo

Key	Value
State	1 (0x1)
Online Mode	1 (0x1)
Run number	2
Transition in progress	0 (0x0)
Start abort	0 (0x0)
Requested transition	0 (0x0)

Stop time binary: 1515425122 (0x5A538D62)

Histogram Data

Scatter-plot

Customized scatter plot

Color Map

Custom Page

!!!!!! Please do not touch unless you are asked by an expert!!!!

Xe pressures

Control: ON | OFF

Detector: 1000F

GM ref.: 1000L

ESx particle

Bottom loader

ESx particle

Introduction

Signal manipulation

Triggering

Wiring and crates

DAQ frameworks

Software and firmware

Example experiments

Software

- Any non-trivial experiment requires custom DAQ software
 - Data readout, event building, realtime analysis, ...
- Language depends on your DAQ framework
- May need to write low-level code to talk to devices
 - C functions, register maps, sockets, memory buffers
 - Some vendors provide higher-level libraries

Software - Python

- Easy to learn with rich ecosystem of libraries in PyPI
 - E.g. python-vxi11 for talking to many DAQ devices
- Slower to execute compared to C/C++
 - Can (carefully) call C code/libraries from Python
- Added python support to midas a few years ago
 - Very popular, especially for low-data-rate applications
 - Correct usage of numpy can make code much faster

Software - C/C++

- Compile your software, then run it
 - Compiler is your friend, not your enemy
 - Try to fix all warnings/errors
- You need to know a little more about memory, pointers
 - "New" smart pointers make memory usage safer
 - `std::shared_ptr` etc.
- Modern C++ has many features
 - Keep it simple



Software - development tips

- Write code that is readable!
 - Make your life as easy as possible when you need to debug/extend
- Try to separate layers of complexity
 - Don't obscure the high-level algorithm with low-level implementation details
- Give your functions sensible names
 - The principle of least surprise
- Document the *why* not the *what*

Software - outsourcing to AI

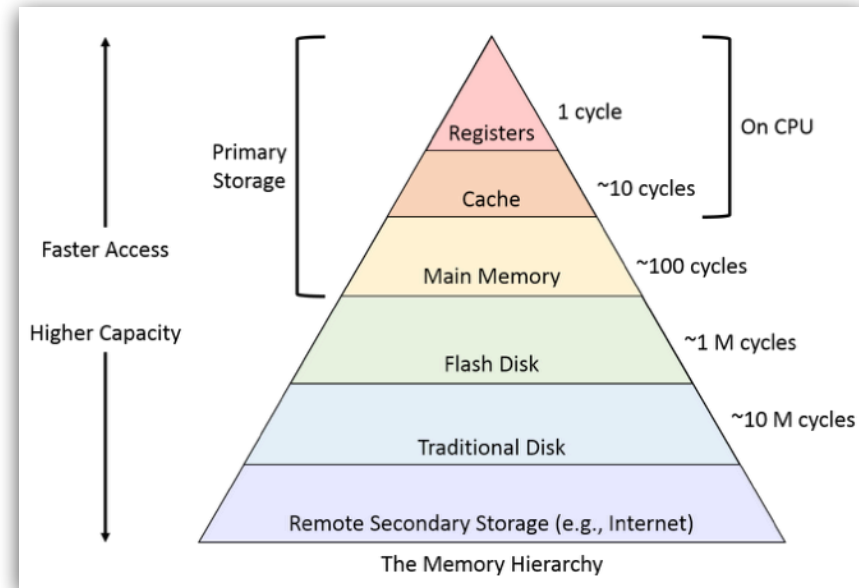
- ChatGPT / CoPilot / Claude / Cursor can generate code
- *May* generate working code quickly
- It can be excellent for smaller tasks
 - E.g. how to add a label to a plot in matplotlib / ROOT
- I think it's a long-term risk for bigger tasks
 - Sometimes it's wrong, or does the right thing in a weird way
 - Harder to maintain/explain/standardise AI-gen code
 - Normally at least 1 person understands the codebase (the original author) - now it may be 0?
- Ask me to rant about "vibe coding" when we're at the pub...

Software - testing

- Test any code you write!
 - Just because your code compiles doesn't mean it's correct...
 - Ensure you don't introduce "regressions" as code evolves
- Strongly consider testing frameworks
 - unittest module for Python
 - Catch2/GoogleTest for C++
 - May want to write a dummy/mock device so you can run tests without talking to real hardware devices
- I structure my code so I can test ~99% of it on my laptop

Software - getting faster

- You can (almost) always make your code faster
 - Use a more efficient algorithm
 - Use a compiled language
 - Buy more/faster computers
 - Optimise your in-memory data layout/usage
 - Use a GPU (for very parallel problems)
 - Write firmware

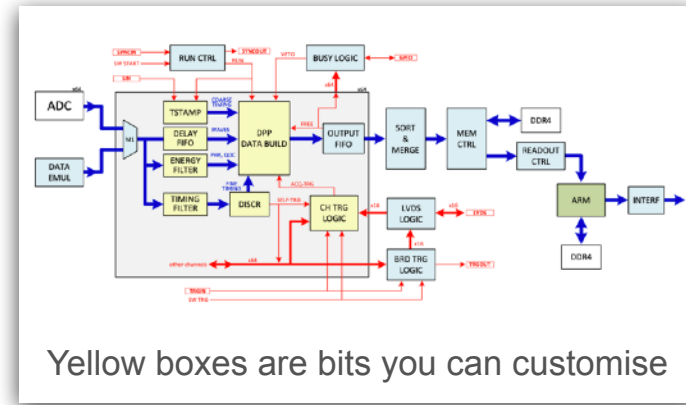


Software vs firmware

- Software runs on a general purpose PC
 - You don't have tight control over what happens when
 - You can try to declare yourself as a "high priority" program, but the OS still decides how much CPU time each program can have
- Firmware runs on dedicated hardware
 - Your code defines what should happen every single clock cycle (multiple instructions possible)
 - You know *precisely* what will happen 100 million times per second (for 100MHz clock)

Firmware development

- Hardware design languages - VHDL/SystemVerilog
- Writing firmware code takes a LOT longer than software
- Generally an engineer-level position
- BUT companies are starting to offer "open firmware" solutions, e.g. CAEN OpenFPGA
 - CAEN write most of the firmware, but allow you to implement some custom logic
 - They provide a development kit to make your work easier



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Reminder of our building blocks

Signal manipulation

- Amplifier
- Noise filter
- Stretching
- Summation

Digitisation

- Discriminator
- Scaler/MCS
- TDC
- Digitiser/ADC

Digital logic

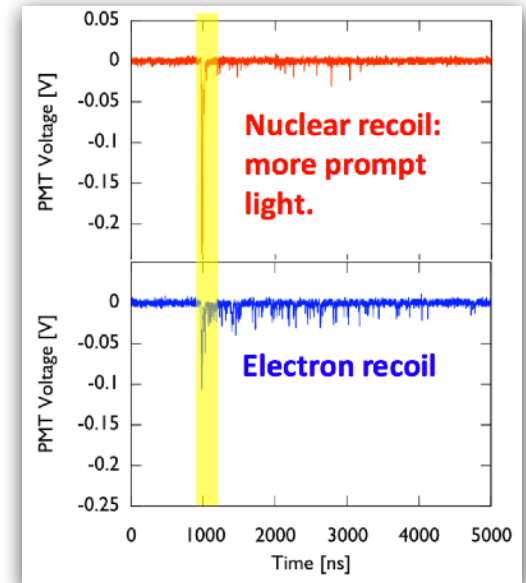
- Coincidence (AND)
- Fan-in (OR)
- Inverter (NOT)

Custom code

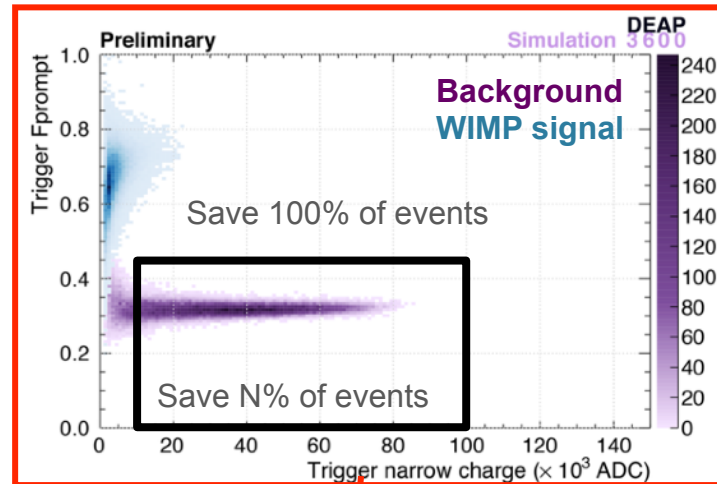
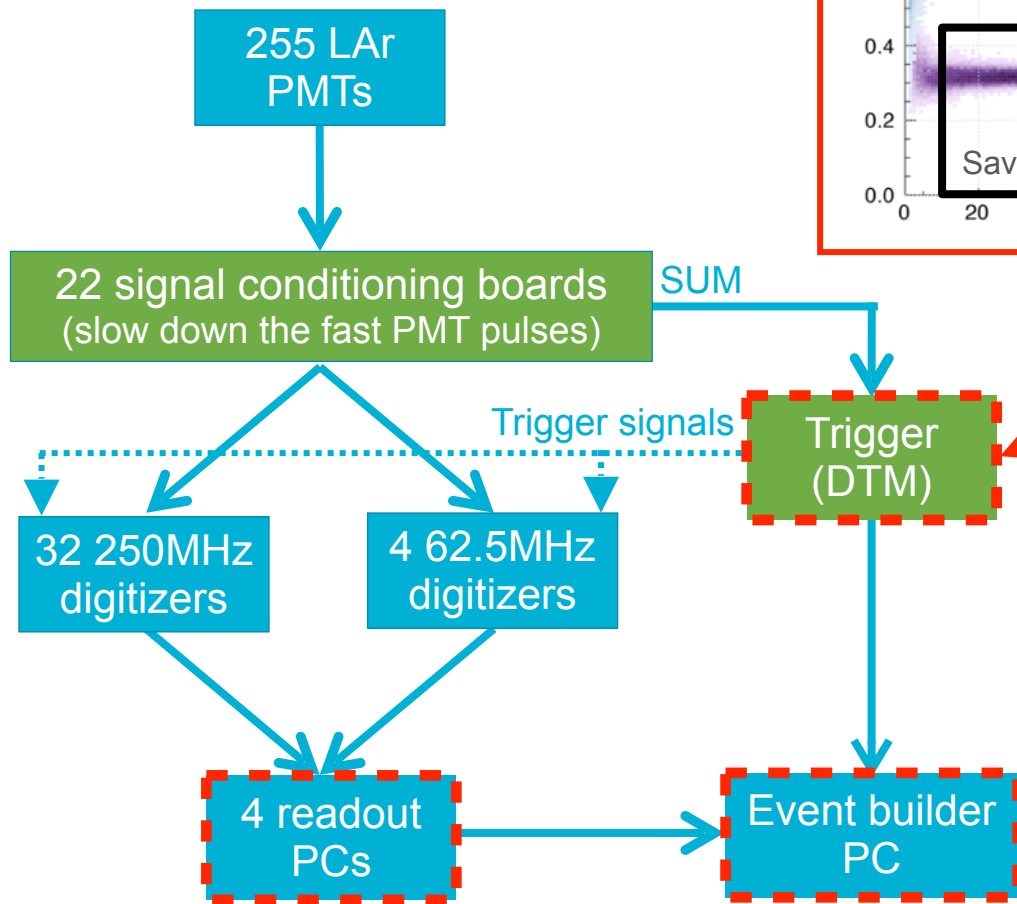
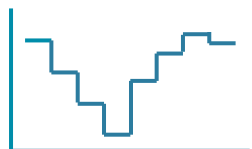
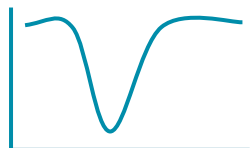
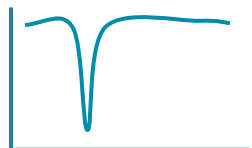
- Firmware
- Software

Example 1 - DEAP-3600

- Dark matter search - 255 PMTs in LAr
- High background rate (kHz)
- Distinguish signal/background using energy and time distribution of photons
 - Need to record detailed info for signal-like events
- Runs 24/7 for many years
 - Need to suppress background
 - Trigger needs custom firmware



Example 1 - DEAP-3600



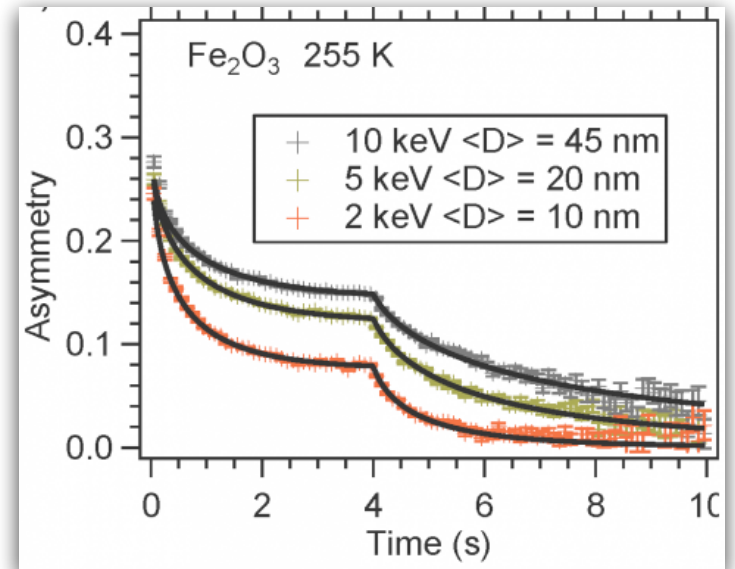
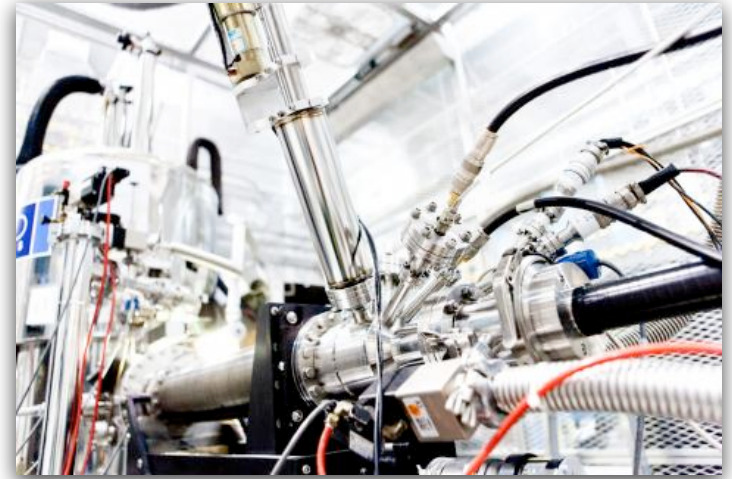
Custom hardware

Commercial hardware

Custom software/
firmware

Example 2 - BNMR

- Beamline experiment for condensed matter and material science
- Inject ions, count beta decays as a function of time
- Complex timing schemes for ion beam, RF, lasers
 - Different for each experiment and sample



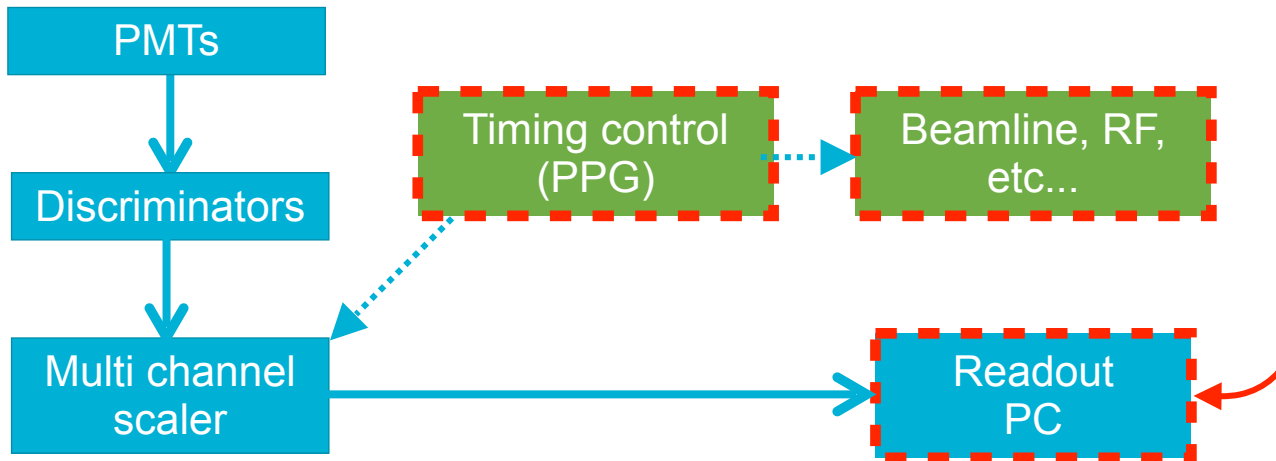
Example 2 - BNMR

- Hardware is relatively simple
- Complexity is in the software
- Good user interfaces can greatly improve efficiency

Custom hardware

Commercial hardware

Custom software/
firmware



Conclusion

- DAQ links the hardware and data analysis
 - Tools for operating and validating the experiment
 - Knowledge of DAQ needed for proper data analysis
- Many decisions to make based on physics needs/budget
 - Important to consider this early in design process
- Lots of DAQ frameworks, but I recommend midas
- DAQ software spans low-level device communication through high-level user interfaces
- Test your code - your analysis depends on it!